



# mL-MFU6 72 x 72 DIN Size Universal Input Programmable Timer & Counter with Output Module System

- 6 digits Process (PV) and 6 digits Set (SV) Value Display
- Operation with 2 Set Value
- Reset , Pause and ChA-ChB Counting Inputs
- Configurable Counter / "Totalizer Counter", Batch Counter, Timer, Chronometer, Frequencymeter and Tachometer Functions
- Programmable Time Bases for Timer and Chronometer (Second , Minute , Hour )
- Operation with Automatic and Manual Reset
- Output Module System
- NPN/PNP Type Operation
- INC , DEC , INC / INC , INC / DEC , UP / DOWN , x1/x2/x4 Counting with Phase Shifting Property in Counter Function
- Multiplication Coefficient and Decimal Point Position
- Different Alarm Alternatives in Frequencymeter and Cycle Measuring Functions
- Absolute or Offset Operation in Counter Function
- RS-485 Serial Communication with Modbus ASCII or RTU Protocol

### **ABOUT INSTRUCTION MANUAL**

Instruction manual of mL-MFU6 Programmable Timer&Counter consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in "CONTENTS" section. User can reach to any title with section number.

#### Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, module mounting in the device, physical and electrical installation of the device to the system are explained.

### **Operation and Parameters:**

In this section, user interface of the device, how to access to the parameters, description of parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.



This symbol is used for safety warnings. User must pay attention to these warnings.



This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.



This symbol is used to determine the important notes about functions and usage of the device.

	CO	N		N	I	
_		_	_		_	_

1.PREFACEPage 6 1.1 GENERAL SPECIFICATIONS 1.2 ORDERING INFORMATION 1.3 WARRANTY 1.4 MAINTENANCE	;
2.INSTALLATION	•
3.ELECTRICAL WIRINGS	5
3.5 GALVANIC ISOLATION TEST VALUES OF mL-MFU6 PROGRAMMABLE TIMER&COUNTER AND OUTPUT MODULES	
4.DEFINITIONS AND SPECIFICATIONS OF OUTPUT MODULES	2
5.CONNECTION TERMINALS OF OUTPUT MODULES AND CONNECTION	
WIRINGPage 27 5.1 RELAY OUTPUT MODULE CONNECTION 5.2 SSR DRIVER MODULE CONNECTION 5.3 DIGITAL (TRANSISTOR) OUTPUT MODULE CONNECTION	7
6.CONNECTIONS FOR RS-232 / RS-485 SERIAL COMMUNICATION	}
7.DEFINITION OF FRONT PANEL AND ACCESSING TO THE SET	
PARAMETERSPage 33 7.1 DEFINITION OF FRONT PANEL 7.2 POWER ON OBSERVATION OFmL-MFU6 PROGRAMMABLE TIMER & COUNTER AND SOFTWARE REVISION ON THE DISPLAY	5

10.SPECIFICATIONSPage 103
9.FAILURE MESSAGES IN mL-MFU6 PROGRAMMABLE TIMER & COUNTER Page 101
B.PROGRAM PARAMETERSPage 68
7.10 ACCESSING TO THE PROGRAM PARAMETERS
7.9 CHRONOMETER PARAMETERS 7.9.1 CHRONOMETER APPLICATIONS EXAMPLES
7.8 FREQUENCYMETER / TACHOMETER PARAMETERS 7.8.1 FREQUENCYMETER / TACHOMETER APPLICATIONS EXAMPLES
7.7 TIMER PARAMETERS 7.7.1 TIMER APPLICATIONS EXAMPLES
7.6 BATCH COUNTER PARAMETERS 7.6.1 BATCH COUNTER APPLICATIONS EXAMPLES
7.5 COUNTER / "TOTALIZER COUNTER" PARAMETERS 7.5.1 COUNTER / "TOTALIZER COUNTER" APPLICATIONS EXAMPLES
7.4 RESETTING COUNT VALUE AND OBSERVING TOTAL COUNT VALUE IN COUNTER / "TOTALIZER COUNTER" FUNCTION

7.3 ADJUSTMENT OF SET1 AND SET2 VALUES

### 1.Preface

mL-MFU Series Programmable Timer & Counter can be used in package machines, production and quality control rollers, in cutting and processing machine of glass, plastic, marble, sheet, iron, fabric all measuring and controlling of dimension, count, total count, speed, cycle, productivity, time and can be adapted easily to all mechanical construction and automation system. They can be used in many application with their control outputs, serial communication unit and output modules.

Some application fields which they are used are below:

**Application Fields** 

Glass

Plastic

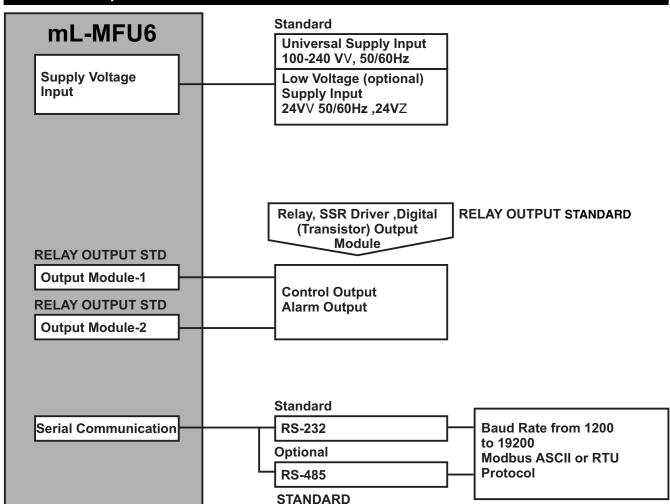
Marble

Sheet iron

Automative

Machine production industries

# 1.1 General Specifications



# 1.2 Ordering Information

Model Number	Description		
mL-MFU6	Programmable Timer & Counter with Output 115 VAC (±15%) 50/60Hz - 1.5VA Rs485 Serial Communication 2 Relay Outputs (3A @ 250 VAC ~ Resistive Load)		

# 1.3 Warranty

This product is warranted against defects in materials and workman-ship for a period of two (2) years from the date of shipment to Buyer.

The Warranty is limited to repair or replacement of the defective unit at the option of the manufacturer. This warranty is void if the product has been altered, misused, dismantled, or otherwise abused.

ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, ARE EXCLUDED, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE.

### 1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.

Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

### 2.Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

### In package,

- -One piece unit
- Two pieces mounting clamps
- One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

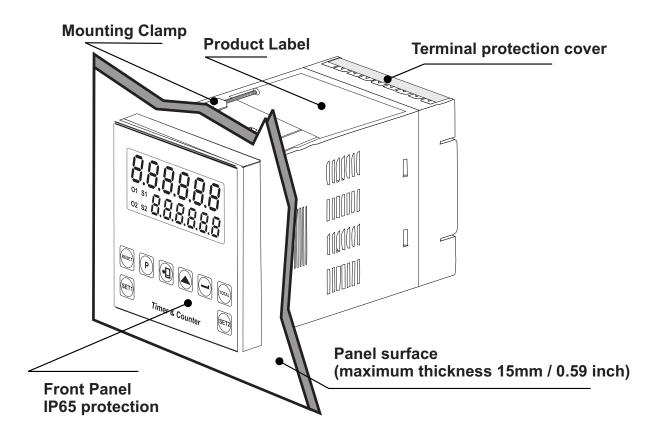
Do not use the unit in combustible or explosive gaseous atmospheres.

During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

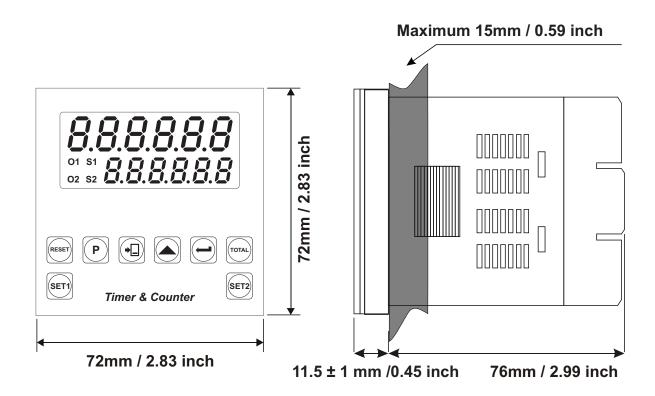
Mounting of the product on a system must be done with it's fixing clamps. Do perform the mounting of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

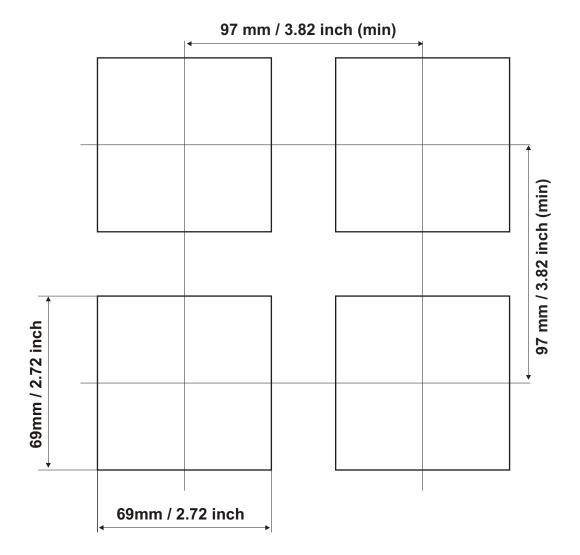
It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

# 2.1 General Description



# 2.2 Dimensions





### 2.4 Environmental Ratings

### **Operating Conditions**



**Operating Temperature** : 0 to 50 °C



Max. Operating Humidity: 90% Rh (non-condensing)

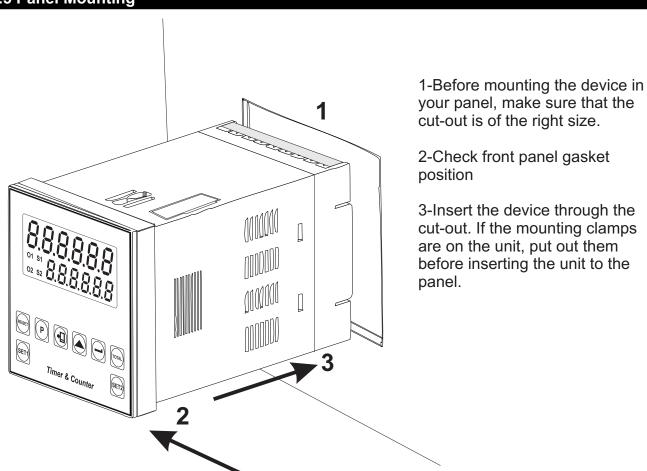


**Altitude** : Up to 2000m.



Forbidden Conditions:
Corrosive atmosphere
Explosive atmosphere
Home applications (The unit is only for industrial applications)

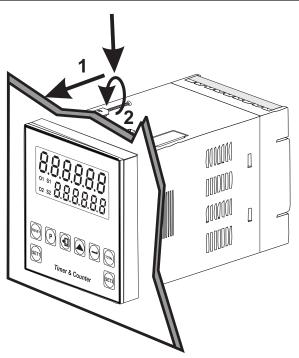
### 2.5 Panel Mounting





During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.

# 2.6 Installation Fixing Clamp



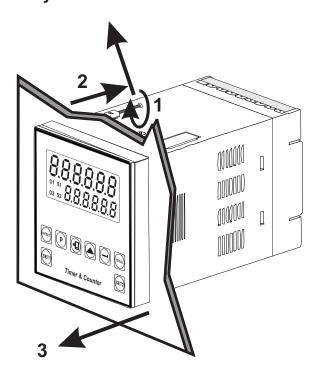
The unit is designed for panel mounting.

- 1-Insert the unit in the panel cut-out from the front side.
- 2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel

Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

### 2.7 Removing from the Panel

Before starting to remove the unit from panel, power off the unit and the related system.

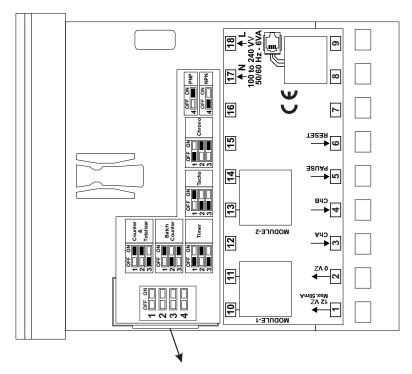


- 1-Loosen the screws.
- 2-Pull mounting clamps from top and bottom fixing sockets.
- 3-Pull the unit through the front side of the panel

# 2.8 Selection of Operation Function and Input Type with DIP Switch

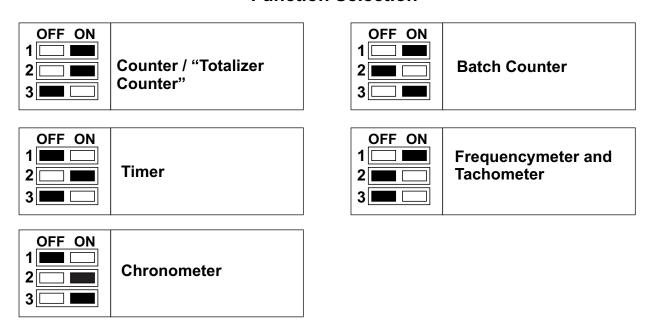


Operation function and input type ( NPN / PNP ) can be changed by DIP switch on the device.



DIP Switch is under cover and cover is on top side of the device

### **Function Selection**



# **Input Type Selection**

OFF ON	NPN	OFF ON	PNP

### 3. Electrical Wirings



You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.

Parameters of the device has factory default values. These parameters must be set according to the system's needs.



Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.

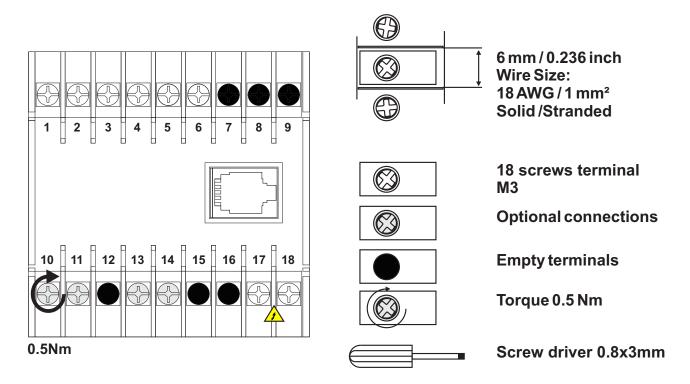


Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.



Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

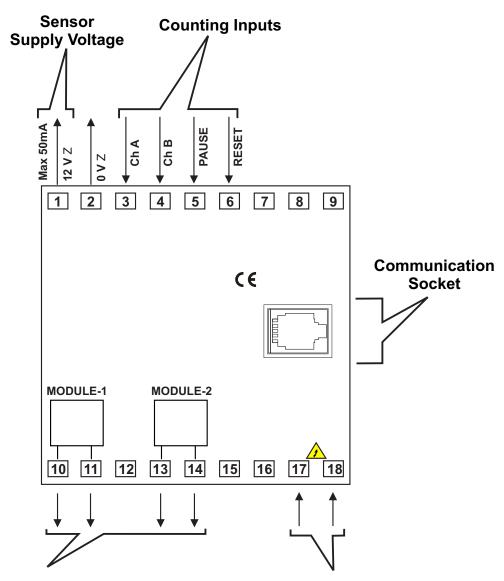
# 3.1 Terminal Layout and Connection Instructions



### 3.2 Electrical Wiring Diagram



Electrical wiring of the device must be the same as 'Electrical Wiring Diagram' below to prevent damage to the process being controlled and personnel injury.



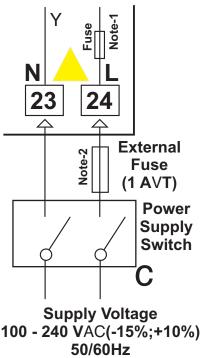
Output Module Terminals Relay Output Module STANDARD Supply Voltage Input 100-240VAC(-15%;+10%) 50/60Hz - 6VA STANDARD

SSR Driver Module
Digital (Transistor) Output Module

24 VAC(-15%;+10%) 50/60Hz - 6VA 24VDC (-15%;+10%) - 6W

### 3.3 Connection of Device Supply Voltage Input

### Connection of Universal Supply Voltage Input



#### Note-1:

There is internal 33R W fusible flameproof resistor in 100-240 VAC 50/60Hz There is internal 4R7 W fusible flameproof resistor in 24VAC 50/60Hz and 24VDC **Note-2:** External fuse is recommended.



Make sure that the power supply voltage is the same indicated on the instrument.

Switch on the power supply only after that all the electrical connections have been completed.

Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.



There is no power supply switch on the device. So a power supply switch must be added to the supply voltage input. In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument. Power supply switch shall be easily accessible by the user.

Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical connection. On/Off condition of power switch must be signed for preventing the wrong connection.

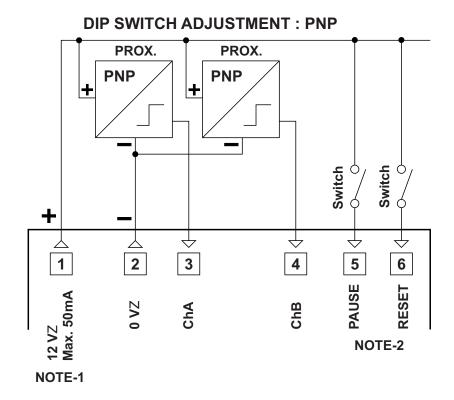
If an external fuse is used, it must be on phase connection in Vsupply input.

If an external fuse is used, it must be on (+) line connection in Zsupply input.



The instrument is protected with an internal fuse (Please refer to Note1 for information). In case of failure it is suggested to return the instrument to the manufacturer for repair.

# 3.4.1 Proximity & Switch Connection



\_\_\_\_\_\_

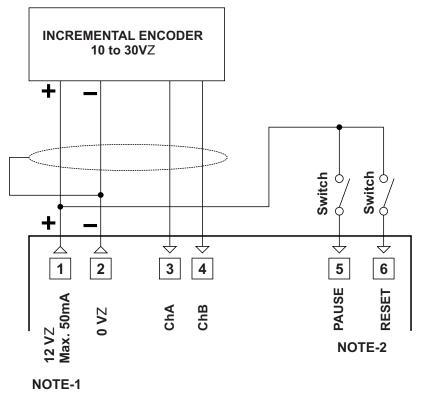
# **DIP SWITCH ADJUSTMENT: NPN** PROX. PROX. **NPN NPN** + 2 1 3 4 5 6 **PAUSE** RESET ZV 0 ChA **NOTE-2 NOTE-1**

NOTE-1 : Auxiliary power supply for external transmitter  $12VZ \pm 10\%$ , 50 mA maximum with short circuit protection

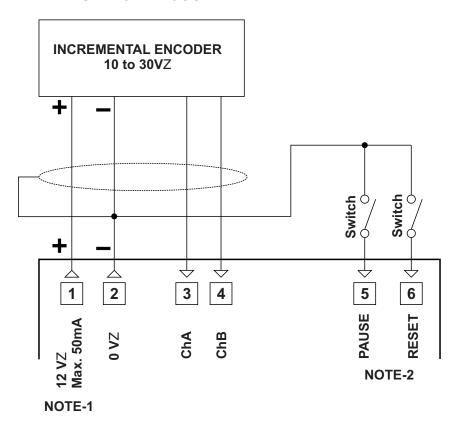
NOTE-2: Reset and Pause inputs have protection time against electrical contact debounce. Protection time can be set with  $| P_{CQ} - | Q_{Q} |$  parameter. (2-250 msec.)

### 3.4.2 Incremental Encoder & Switch Connection



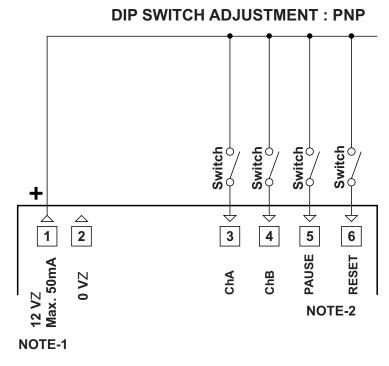


### **DIP SWITCH ADJUSTMENT: NPN**



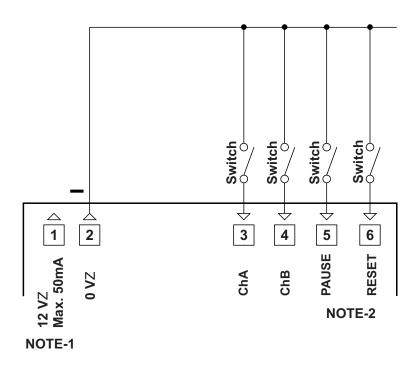
NOTE-1: Auxiliary power supply for external transmitter 12VZ ± 10%, 50 mA maximum short circuit protection

NOTE-2: Reset and Pause inputs have protection time against electrical contact debounce. Protection time can be set with  $| P_{CQ} - | P_{CQ} |$  parameter. (2-250 msec.)



.....

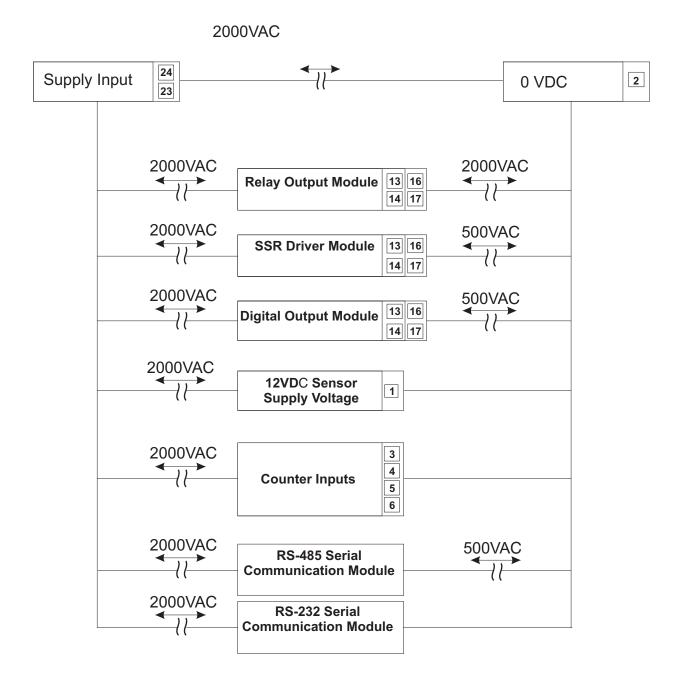
### **DIP SWITCH ADJUSTMENT: NPN**



NOTE-1: Auxiliary power supply for external transmitter 12VZ ± 10%, 50 mA maximum short circuit protection

NOTE-2 : Reset and Pause inputs have protection time against electrical contact debounce. Protection time can be set with [무ㄷㅁ - [] 닉] parameter. (2-250 msec.)

# 3.5 Galvanic Isolation Test Results of mL-MFU6 Programmable Timer & Counter and Output Modules

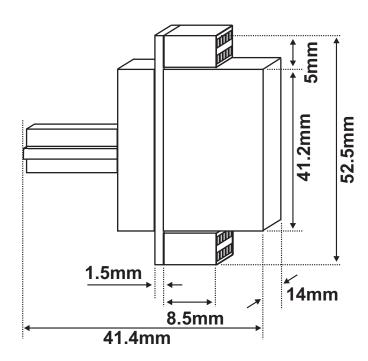


### 4. Definitions and Specifications of Output Modules

mL-MFU6 programmable Timer &Counter is a modular product which is designed to operate with additional output units which user may need.

Two output modules can be plugged in the equipment by the user. User may configure the product for different applications according to the system requirements with the output modules which are described in this section.

### **Dimensions of Output Modules**



### 4.1 Relay Output Module

Relay output module can be plugged in Module-1 or Module-2 socket to be used in applications that relay output is necessary

**Specifications of Relay Output Module** 

Output : 3A @ 250VAC , Single Open Contact

**Dimensions** : 14x30.7x41.4mm

Electrical Life : 100.000 operation (Full Load)

# **Applications of Relay Output Module**

It can be used for programmable different alarm functions as control or alarm output.

### 4.2 SSR Driver Module

SSR Driver Module can be plugged in Module-1 or Module-2 socket to be used in applications that SSR driver output is necessary

**Specification of SSR Driver Module** 

Output: Maximum 26 mA, 22VDC ±10%, isolated

**Dimensions:** 14x30.7x41.4mm

### **Applications of SSR Driver Module**

It can be used for programmable different alarm functions as control or alarm output.

<u>Note 1:</u> SSR Driver Module must be preferred instead of relay output module in applications with short output period because of limited life of their relay contact (number of open/close events).

### 4.3 Digital (Transistor) Output Module

Digital (Transistor) Output Module can be plugged in Module-1 or Module-2 socket to be used in applications that digital output is necessary

# **Specifications of Digital (Transistor) Output Module**

Output: Maximum 40 mA, 15-18VDC ±10%, isolated

**Dimensions:** 14x30.7x41.4mm

### **Applications of Digital (Transistor) Output Module**

It can be used for programmable different alarm functions as control or alarm output.

### 4.4 Installing and Pulling Out Output Modules



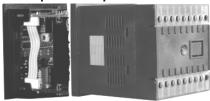
First, detach all cable connections from the device and uninstall it from the panel.

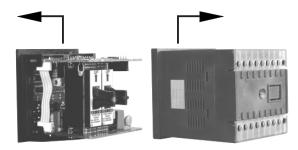


Suppress to the lock pins where top and bottom of the device

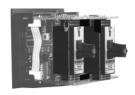


Pull the cover case with your other hand from front panel to rear side.





Pull out the cover case from the device



Slide output modules into socket.

Pull out the module from it's socket, instead of this module install the new one or other module user wants to use.



Replace the cover case by taking care of the terminal numbers should be at right position.

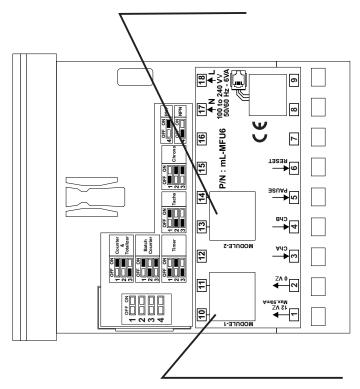


After adding or changing modules to the unit, these changes must be taken into consideration while mounting of the unit to the system. If mounting is incorrect, it can cause accidents to harm system, operator or person who does the mounting. Responsibility of these kind of harmful events belongs to the user.

# 4.5 To Stick Output Modules' Labels to the Equipment

Every module which is plugged in Module-1 or Module-2 socket has labels' for showing the relation between connection terminal and the device. These labels are attached to empty attachment places which are separated for Module-1 and Module-2 on the device. Labels for all modules and attachment places are shown below.

Label which is plugged in Module-2 socket, describes module termination connection is attached to this area.



Label which is plugged in Module-1 socket, describes module termination connection is attached to this area.

### LABELS FOR OUTPUT MODULES



**Label for Relay Output Module** 

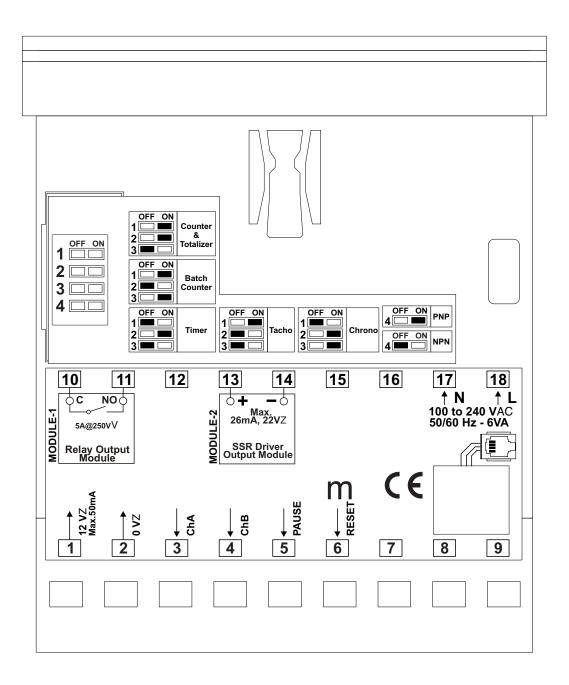


**Label for SSR Driver Module** 



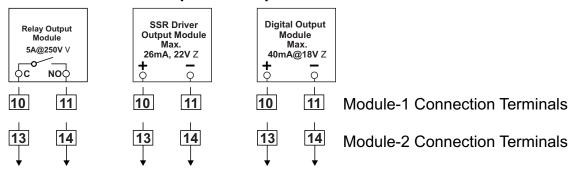
**Label for Digital (Transistor) Output Module** 

**Example:** If user installs Relay Output Module to Module-1 socket, SSR Output Module to Module-2 socket and attach the appropriate labels on the device view will be like below:

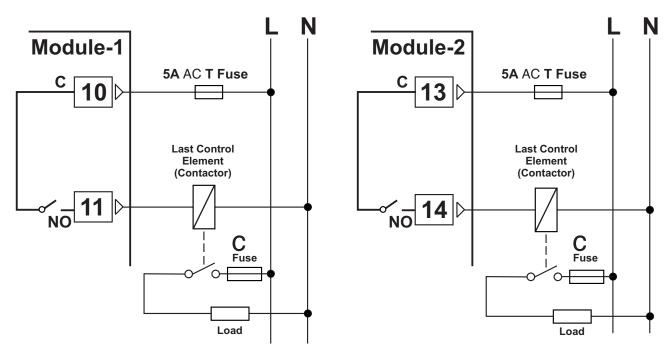


# 5. Connection Terminals of Output Modules and Connection Wirings

### Module-1 / Module-2 Optional Output Modules

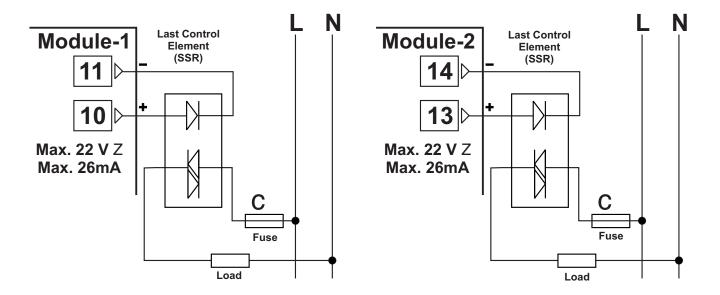


### 5.1 EMO-700 Relay Output Module Connection



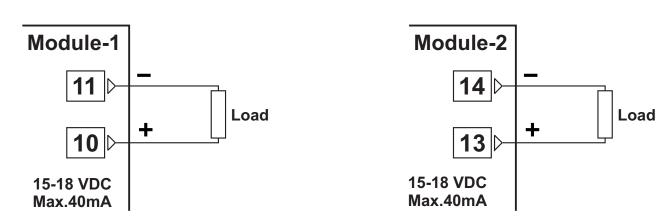
Fuses must be selected according to the applications.

# **5.2 SSR Driver Module Connection**



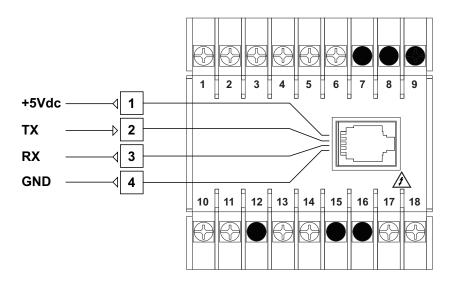
Fuses must be selected according to the applications.

# 5.3 Digital (Transistor) Output Module Connection

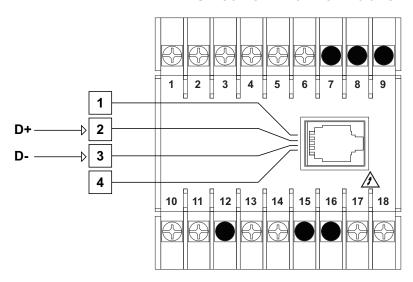


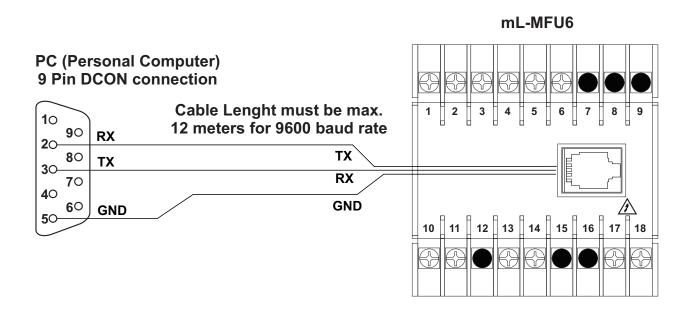
# 6.Connection for RS-232 / RS-485 Serial Communication

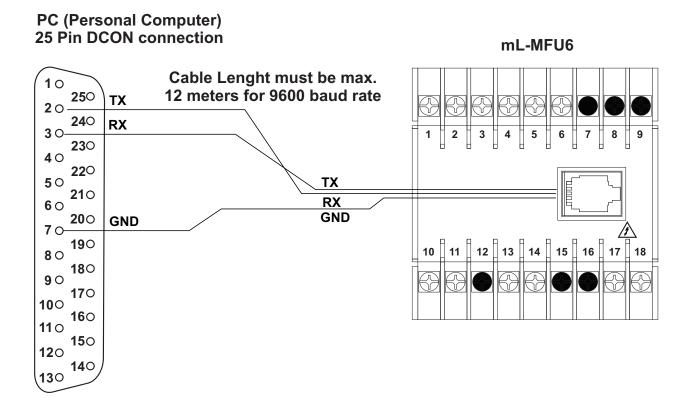
### **RS-232 Terminal Definitions**



### **RS-485 Terminal Definitions**

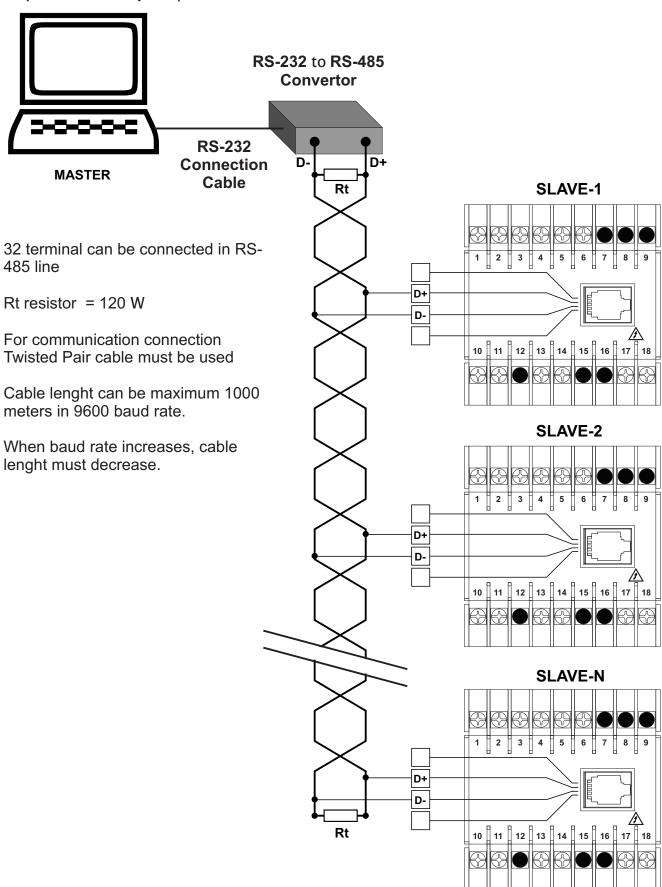






### 6.2 Connection for RS-485 Serial Communication

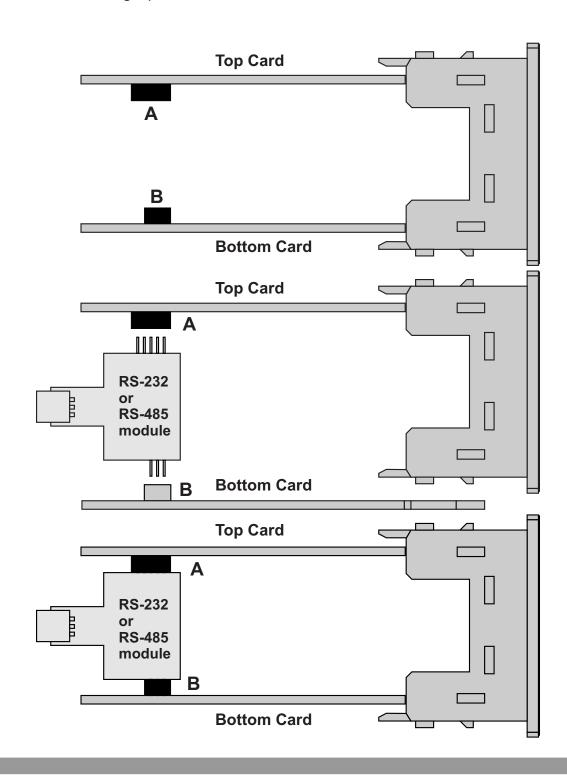
### **PC(Personal Computer)**



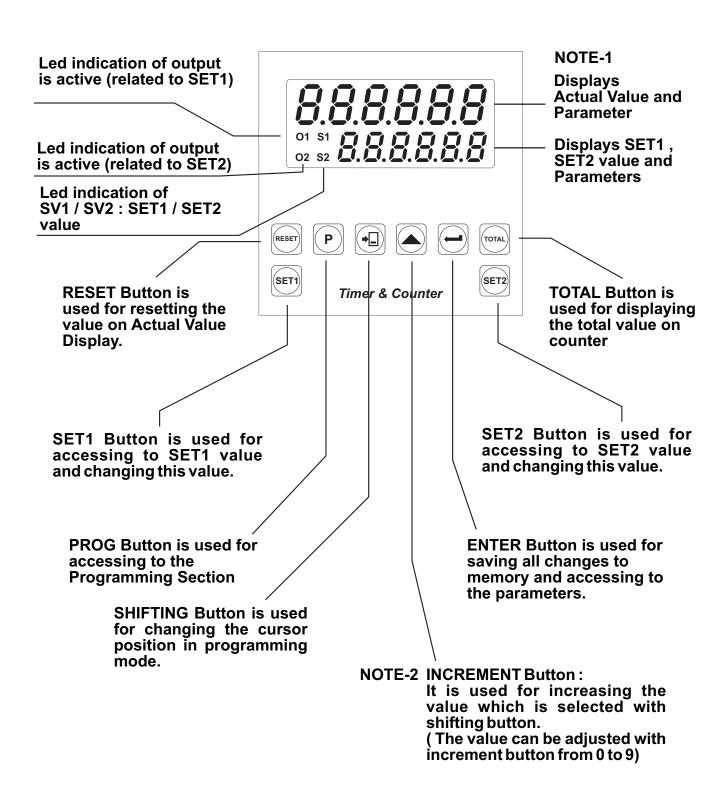
### 6.3 Installing RS-232 / RS-485 Serial Communication Modules to the Device

Pull the cover case with your hand through rear side as explained in "Installing and Pulling Out Output Modules" section. Pull the modules in Module-1 and Module-2 socket through rear side. Separate supply card which is at the bottom of the equipment by lifting the locking tabs located on front panel. Pay attention to cable connection between top and bottom cards. Damages in this cable makes the equipment not to work.

RS-232 or RS-485 module is plugged into socket signed as A and B. Hold the equipment to be it's front panel is on your right, communication socket is on your left and module connection socket with 5 terminals on above. Plug in module connection socket with 5 terminals to the socket on Top Card. Do the same things for terminal socket in bottom card and connection socket with 3 terminals. Plug in bottom card to the place in front panel. Install the modules which are pulled out to Module-1 and Module-2 socket. Replace the cover case by taking care of the terminal numbers should be at right position.



### 7.1 Definition of Front Panel

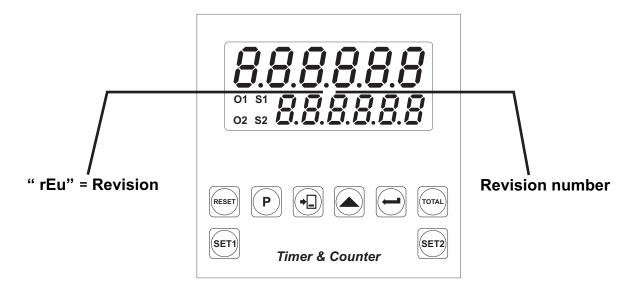


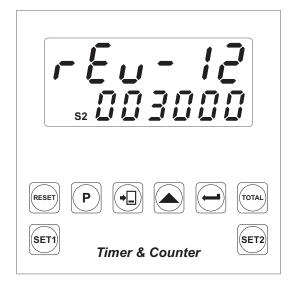
NOTE-1: Total count value is 12 digits in Counter / "Totalizer Counter" function

# 7.2 Power On Observation ofmL-MFU6 Programmable Timer & Counter and Software Revision on the Display

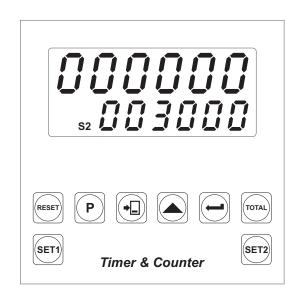
When power is applied to the device, software revision number of the controller is momentarily illuminated on actual value display. Then operation screen is observed.

When power on, view of the screen is shown below:









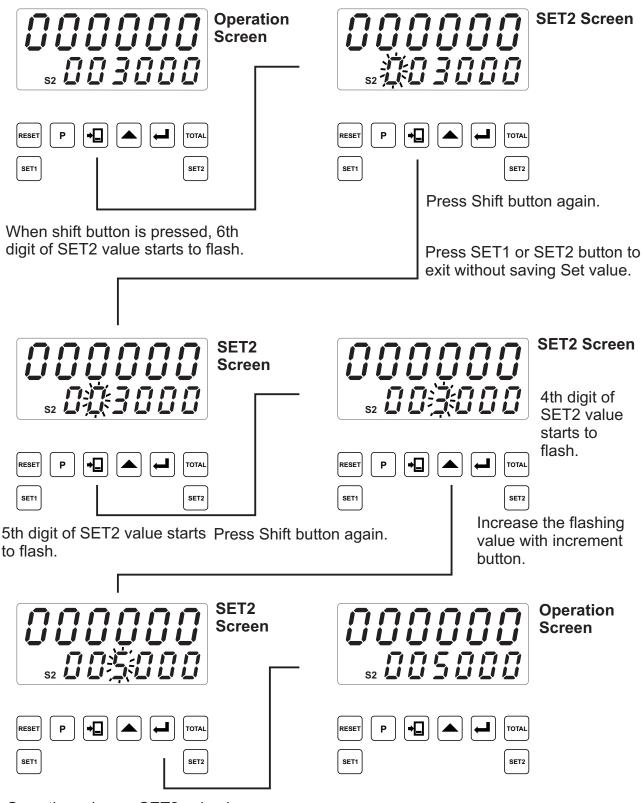
Operation Screen is shown



If there is an unexpected situation while opening the device, power off the device and inform a qualified personnel.

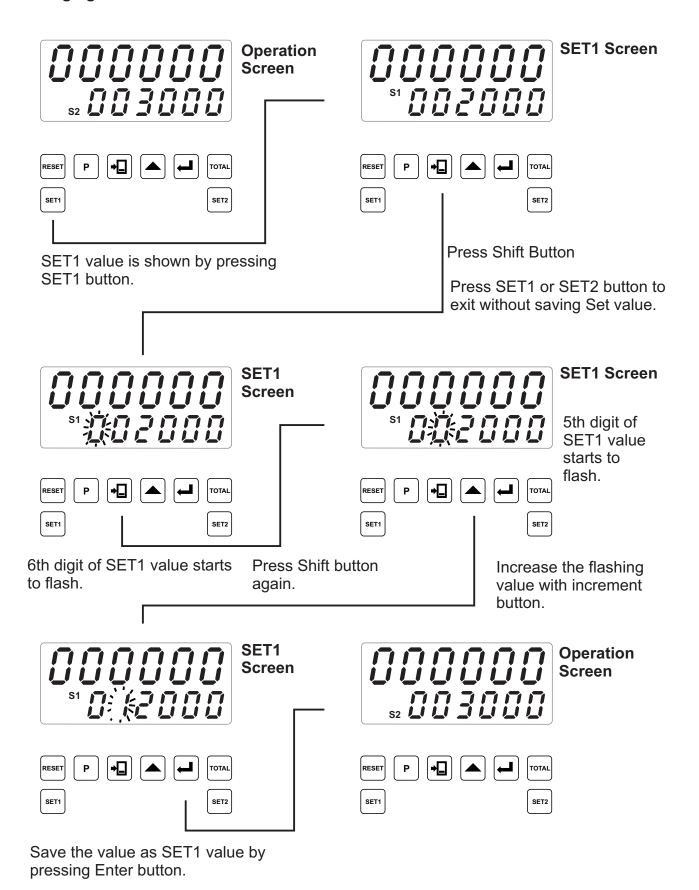
### 7.3 Adjustment of SET1 and SET2 Values

Changing SET2 value in Counter / "Totalizer Counter" functions



Save the value as SET2 value by pressing Enter button.

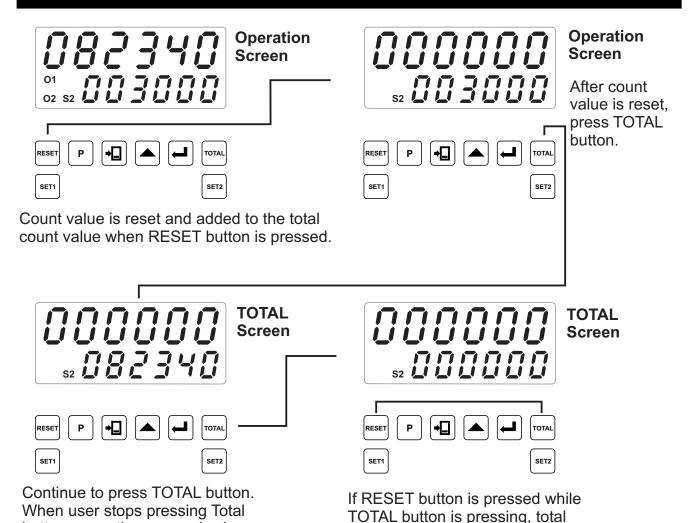




(i)

If Pro-28 Reset and Set Protection parameter is [][][][][]], then SET1 value can not be changed. For details, refer to parameters section.

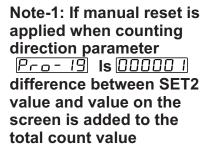
# 7.4 Resetting Count Value and Observing Total Count Value in COUNTER / "TOTALIZER COUNTER" Function



Total count value is 12 digits.

button, operation screen is shown.

When user stops pressing the buttons, operation screen is shown.







### **Operation Screen**

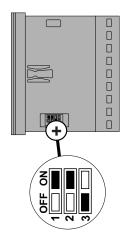


If  $P_{-0}$  - 28 Reset and Set Protection parameter is 000001 or 000003 then total count value can not be reset. For details, refer to parameters section.

count value is reset.



RESET operation can be realized by Reset button or applying signal to the RESET input. These two operations are named MANUAL RESET in parameters section. At the end of the MANUAL RESET operation, if counting direction parameter  $\boxed{Pro-19}$  is  $\boxed{000000}$  then count value becomes  $\boxed{000000}$ . If counting direction parameter  $\boxed{Pro-19}$  is  $\boxed{000000}$  then count value becomes equal to SET2 value.



### 7.5 COUNTER / "TOTALIZER COUNTER" Parameters

SET1

If SET1 operation form selection parameter  $P_{-0}$  - 22 is selected operation with offset 00000 , it can be adjusted from 999998

SET2

# 

### **Input Types and Functions**

Upcount on rising edge of Ch-Ainput(INC)

Downcount on rising edge of Ch-Ainput(DEC)

Upcount on rising edge of Ch-A input and downcount on rising edge of Ch-B input (INC / DEC)

Upcount on rising edge of Ch-A and Ch-B inputs (INC / INC)

Upcount on rising edge of Ch-A input when Ch-B is at 0, downcount on rising edge of Ch-A input when Ch-B is at 1.(UP / DOWN)

x1 phase shifting (for incremental encoders)

x2 phase shifting (for incremental encoders)

x4 phase shifting (for incremental encoders)

## P-0-04

## Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

## Pro-05

#### **Output Functions**

Manual Reset-1. Device continues to count till manual reset is applied.

Output-2 pulse time Pro-17 is not considered.

Manual Reset-2. Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time Pro-17 is not considered.

Manual Reset-3. It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.



000003	<b>Automatic Reset-1.</b> Count value is reset when it reaches to SET2 value (For 0->P). Count value is added to total count value and device starts to count from DDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD
000004	Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value becomes zero (for 0->P) at the end of output-2 pulse time Pro-17 And count value is added to total count value. Device starts to count from [][][][][][][][][][][][][][][][][][][]
000005	Automatic Reset-3. Count value becomes zero (for 0->P) when it reaches to SET2 value and count value is added to total count value. Device starts to count from [][][][][][] . Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time [Pro-17]
000006	<b>Automatic Reset-4.</b> Counting is continued when count value reaches to SET2 value. Count value becomes zero (for 0->P) at the end of Output-2 pulse Pro-17 time and it is added to total count value. Device starts to count from [][][][][][][][][][][][][][][][][][][]
000007	<b>Automatic Reset-5.</b> Counting is continued till manual reset is active. Output-1 and Output-2 pulse times ( $P_{\neg \Box} - I_{\Box}$ ) and $P_{\neg \Box} - I_{\Box}$ ) are not considered. It is preferred if upcount and downcount are done at the same time.
( ; ) counti	ration with Manual or Automatic Reset, at the end of the reset operation, if ng direction parameter <u>Pro-19</u> is <u>000000</u> (0->P), count valuenes 0000000. If <u>Pro-19</u> is 00000000000000000000000000000000000
Pco- 14	Operation form for Output-1
	Output - 1 Normally non-energised
000001	Output - 1 Normally energised
Pro- 15	Operation form for Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 15	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from \$\text{DDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD
Pco- 17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from [] [] [] [] to [] [] If it is [] [] [] [], then it operates indefinitely.
Pro- 19	Selection of counting direction
000000	Upcount( 0 -> Preset )
00000 1	Downcount(Preset -> 0)

Pro-20	Point Position for display
00000	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pro-2 1	Saving Count Value (Power down back-up)
000000	Count value is saved to memory when power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
P-0-22	Selection of SET1 Operation Form
000000	Operating without offset. It can be adjusted from @@@@@@ to 999998
00000 1	Operating with offset. SET1 can be adjusted SET1 = SET2+SET1
P-o-23	Slave Address
	Device address for serial communication bus. It can be adjusted from \( \begin{align*} \Pi & \Pi
Pro-24	Selection of Modbus Protocol Type
00000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
000000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
000000	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate



-27	Stop Bit
10000	1 Stop Bit
1000 1	2 Stop Bits
-28	Reset and Set protection (Accessing from front panel)
10000	There is no Reset and Set protection
1000 1	Reset Button protection is active
10002	SET1 and SET2 protection is active
10003	Reset Button, SET1 and SET2 protection is active (Full protection)
10004	SET1 protection is active
10005	SET2 protection is active
- 30	Multiplication Coefficient  Count value is multiplied with this value. It can be adjusted from \$\overline{\Omega_0000}\$ to \$\overline{\Omega_9999}\$. If it is \$\overline{\Omega_0000}\$, it has no effect.
	-27 10000 1000 1 -28 10000 10002 10003 10005 -30

# P-0-P5

## **Program Password**

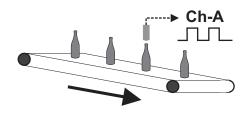
It is used for accessing to the program parameters. It can be adjusted from  $\boxed{000000}$  to  $\boxed{009999}$  . If it is  $\boxed{000000}$ , there is no password protection.



### 7.5.1 COUNTER / "TOTALIZER COUNTER" Applications Examples

### **EXAMPLE-1:**

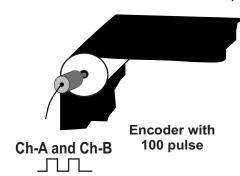
There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If



Counting the bottles is done with upcount by using only Ch-A input. When user reset count value with manual reset, count value is added to total count value.

### **EXAMPLE-2:**

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.



You wish to display 200 in actual value display for a drive pulley going forward of 100 cm. If you want to display cloth length in actual value display, you must adjust coefficient parameter Pro-30 like in below:

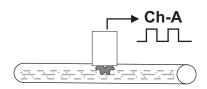
 $P_{-0} - 30$  Coefficient must be = 100/200 = "00.5000"

After adjustment of coefficient, calculated value is cloth length and you can see this value in actual value display.

If you want to display the speed of the drive pulley as dm instead of cm $P_{-a}$  - 20 point position for display parameter must be 00000, if m instead of cm, this parameter must be 00000

### **EXAMPLE-3**:

There is a system like in the diagram below. Ch-A is used for measuring the flow. If

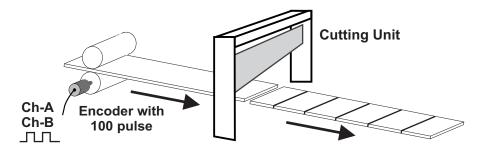


In this application, total amount of flow is measured. If it is known how many pulses are being sent for each liter from the sensor in Ch-A we can measure the desired value by changing the  $\boxed{P_{ \square} - \exists \square}$  parameter.

For example if sensor gives 10 pulses for 1 liter fluid flow and we want to observe the liquid quantity as liter, coefficient parameter  $P_{\Box} - 30$  parameter value must be  $P_{\Box} - 30$  = 1Lt/10 pulse = "00.1000"

#### **EXAMPLE-4:**

There is a cutting unit below. 100-pulse encoder is connected to Ch-A and Ch-B inputs.



If 
$$P_{-0} - 0.1 = 0.00005$$
;  $P_{-0} - 0.0000$ ;  $P_{-0} - 1.9 = 0.00000$ ;  $P_{-0} - 2.2 = 0.0000$ ;  $P_{-0} - 3.0 = 0.0000$ ;

### (SET1=SET1+SET2)

For example; if SET1 = -000100; SET2 = 000500; then SET1 = -100+500 = 400

If more sensitivity is needed,  $P_{CO} - 0$  | parameter can be selected 000000 or 000000

For example, while x1 phase shifting counting is performed in a system with a cutting unit as shown above, a 100-pulse encoder is connected to Ch-A and Ch-B inputs. If the system is advanced 100 cm for 50 encoder pulses, so it is advanced 2 cm with 1 encoder pulse.

When x2 phase shifting counting is performed, for the system is being advanced 100 cm, 100 encoder pulses are needed. In this case, the system is advanced 1 cm with 1 encoder pulse.

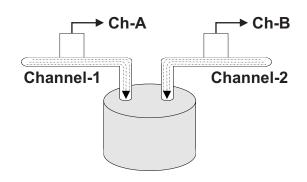
When x4 phase shifting counting is performed, for the system is being advanced 100 cm, 200 encoder pulses are needed. In this case, the system is advanced 0.5 cm with 1 encoder pulse.

Sensitivity of the system is changed from 2 cm to 0.5 cm.

#### **EXAMPLE-5**:

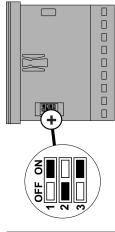
There are two sensors in Ch-A and Ch-B inputs for determining the amount of the liguid in Channel-A and Channel-B. Multiplication coefficient parameter  $P_{-0} - 30$  is adjusted to converts the pulses to observe the amount of the liquid exactly in the actual value screen. (For example liter)

For observing total amount of liquid Pro-01 must be 000003



If the tank is filled with liguid 20 liters from Channel-1 and 40 liters from Channel-2, 60 liters is observed in actual value screen.

If Output-1 controls the Channel-1, Output-2 controls the Channel-2, SET1 is 20 and SET2 is 40, then it is possible to close the system after filling the tank with 20 liters from Channel-1 and 40 liters from Channel-2



### 7.6 BATCH COUNTER Parameters

SET1

SET2

# Pro-0 1

### **Input Types and Functions**

Upcount on rising edge of input Ch-A(INC)

Downcount on rising edge of input Ch-A (DEC)

Upcount on rising edge of input Ch-A and downcount on rising edge of input Ch-B (INC/DEC)

Upcount on rising edge of input Ch-A and Ch-B (INC / INC)

Upcount on rising edge of Ch-A input when Ch-B is at 0, downcount on rising edge of Ch-A input when Ch-B is at 1.(UP / DOWN)

x1 phase shifting (for incremental encoders)

x2 phase shifting (for incremental encoders)

x4 phase shifting (for incremental encoders)

## P-0-04

### Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

It can be adjusted from [10000] to [100250] msec. If it's adjusted to [100000] then there is no time protection for Ch-A and Ch-B. If the parameter value is adjusted [100000] or [100000] then Reset and Pause protection times are accepted as 2 msec.



When SET1 value is shown on the screen if MANUAL RESET is applied, batch count value, when SET2 value is shown on the screen if MANUAL RESET is applied, normal count value becomes zero.





Pro-05	Output Functions
000000	Manual Reset. BATCH counting operation continues until manual reset input is active.
[00000 1]	Automatic Reset.BATCH counting operation continues until Batch count value reaches to SET1 value.When Batch count value is equal to SET1 value,Batch count value becomes zero (for 0->P) and device starts to count again.
Pro- 14	Operation Form of Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation Form of Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 15	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from \$\overline{\text{000000}}\$ to \$\overline{\text{009999}}\$  If it is \$\overline{\text{000000}}\$ , then it operates indefinitely.
Pro- 17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from [] [] [] [] to [] [] If it is [] [] [] [] , then it operates indefinitely.
Pro- 19	Selection of counting direction
000000	Upcount (0 -> Preset )
00000 1	Downcount (Preset -> 0)
Pro-20	Point Position for display
000000	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pro-2 1	Saving Count Value (Power down back-up)
000000	Count value is saved power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
Pro-23	Slave Address
	Device address for serial communication bus. It can be adjusted from [미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미미



Pro-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
000000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
[000000]	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
Pro-27	Stop Bit
000000	1 Stop Bit
00000 1	2 Stop Bits
Pro-28	Reset and Set protection (Accessing from front panel)
000000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	Reset Button, SET1 and SET2 protection is active (Full protection)
000004	SET1 protection is active
000005	SET2 protection is active
Pro-30	Multiplication Coefficient
	Count value is multiplied with this value. It can be adjusted from \( \begin{align*} \Pi &
Pro-P5	Program Password
	It is used for accessing to the program parameters. It can be adjusted from $\boxed{000000}$ to $\boxed{0099999}$ . If it is $\boxed{0000000}$ , there is no password protection.

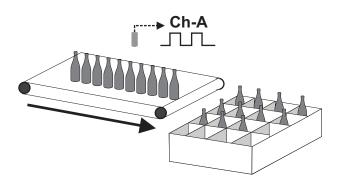


### 7.6.1 BATCH COUNTER Applications Examples

### **EXAMPLE-1:**

There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If

 $P_{-0} - 0 | = 0000000; P_{-0} - 30 = 0 | 000000;$ 

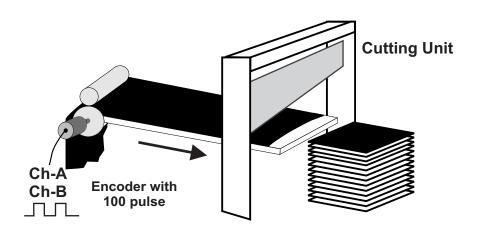


Device is used in a packing line as shown on the left. Bottles must be counted into packs of 4 bottles and dispatched in a box containing a batch of 4 packs. According to this, SET1 and SET2 are defined 4. 4 pieces of packet which contain a batch of 4 series are allowed to be formed.

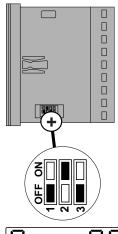
If Pro-DB = DDDDD (Automatic Reset-1); after arranging the bottles in a box as shown on the left, output-1 will be active and it stops the system. Batch count value is reset and it will be ready to count the new series.

#### **EXAMPLE-2:**

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.



Coefficient parameter is adjusted to be able to observe the cloth length in actual value screen. If we want to be cut the cloth in same length at 5 m and stopped the system when 40 pieces of 5 m cloths are formed, SET1 must be 40 and SET must be 5.



### 7.7 TIMER Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be changed by time unit and scale selection parameter Pro-05

SET2



### **Time Unit and Scale Selection**

Hour/Minute

It can be adjusted from 000000 to 009959

Minute/Second

It can be adjusted from  $\boxed{000000}$  to  $\boxed{009959}$ 

It can be adjusted from 000000 to 009999

□□□□□∃ Hour/Minute

It can be adjusted from [100000] to [102359]

0000 Hour

It can be adjusted from 000000 to 099999

|\_\_\_\_\_ Minute

It can be adjusted from [000000] to [099999]

| Second

It can be adjusted from 000000 to 099999

## Pro-06

### **Output Functions**

Manual Reset-1. Device continues to count till manual reset is applied. Output-2 pulse time Pro-17 is not considered.

Manual Reset-2. Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time Pro-17 is not considered.

Manual Reset-3. It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.

Automatic Reset-1. Count value becomes zero (0->P) when it reaches to SET2 value. Count value is added to total count value and device starts to count from [][][][][][]

Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value is becomes zero (0->P) at the end of output-2 pulse time Pro-17 And device starts to count again.



In operation with Manual or Automatic Reset, at the end of the reset operation, if counting direction parameter  $P_{-0} - 19$  is 0 - 0 - 0, count value becomes 0 - 0 - 0. If 0 - 0 - 0 is 0 - 0 - 0, count value becomes SET2.

000005	<b>Automatic Reset-3.</b> Count value becomes zero (0->P) when it reaches to SET2 value. Device starts to count again. Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time Pro-17
000006	<b>Automatic Reset-4.</b> Counting is continued when count value reaches to SET2 value. Count value is becomes zero $(0->P)$ at the end of Output-2 pulse time $Pro-17$ . Device starts to count again.
	<b>Automatic Reset-5.</b> When count value reaches to SET2 value, SET1 changes position, count value becomes zero (for 0->P) Output-1 and Output-2 does not change position position until count value reaches to SET2 value.
( ¿ ) counti	ration with Manual or Automatic Reset, at the end of the reset operation, if ng direction parameter Pro-19 is [[[[[[]]]]]]] (0->P), count value nes [[[[]]]]]]. If [[[]] - 19] is [[[]]]]] (P->0), count value becomes SET2.
Pro- 14	Operation form for Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation form for Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 15	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from \$\textsuperscript{\t
P-0-17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from [] [] [] [] to [] [] If it is [] [] [] [], it operates indefinitely.
Pro- 19	Selection of counting direction
000000	Upcount (0 -> Preset)
00000 1	Downcount (Preset -> 0)
Pro-21	Saving Count Value (Power down back-up)
000000	Count value is saved when power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
Pro-23	Slave Address
	Device address for serial communication bus. It can be adjusted from DDDDD to DDD247



Pro-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
00000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
000000	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
Pro-27	Stop Bit
00000	1 Stop Bit
00000 1	2 Stop Bits
Pro-28	Reset and Set protection (Accessing from front panel)
00000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	Reset Button, SET1 and SET2 protection is active (Full protection)
000004	SET1 protection is active
000005	SET2 protection is active
Pro-P5	Program Password

It is used for accessing to the program parameters. It can be adjusted from  $\boxed{000000}$  to  $\boxed{009999}$  . If it is  $\boxed{000000}$ , there is no password protection.

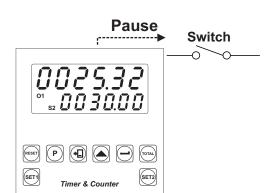


### 7.7.1 Timer Applications Examples

### **EXAMPLE-1:**

There is a switch for giving start and stop signal on PAUSE input.

If  $P_{-0} - 05 = 000001$ ;

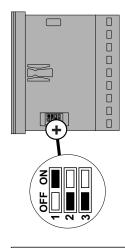


When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.

Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

NOTE: If output-1 and output-2 is wanted to be used as an alarm output;

For example SET1 = 10.00; SET2= 30.00 and  $\boxed{Pro-06} = \boxed{000002}$ Device starts to count (Minute / second) when switch is "On". It is possible to have a warning when SET1 and SET2 times are expired and stopping the alarm at the end of the Output-1 and Output-2 pulse times.(  $\boxed{Pro-16}$  And  $\boxed{Pro-17}$ )



### 7.8 FREQUENCYMETER / TACHOMETER Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be adjusted from [][][][][][] to [999998]

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be adjusted from [][][][][] to 999998



### **Selection of Measurement Method**

Frequency or cycle is calculated by measuring cycle time of the signals in Ch-Ainput

|00000 i

Frequency or cycle is calculated by counting the pulses in Ch-A input during the time is set in measurement period parameter  $P_{-0}$  -  $\square B$ 

## P-0-04

### Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

It can be adjusted from [][][][][][] to [][][][][][] msec . If it's adjusted to [] then there is no time protection for Ch-A and Ch-B. If the parameter value is adjusted 000000 or 000001 then Reset and Pause protection times are accepted as 2 msec.

## |Pro-01

### **Time Out (Input Signal Reset Time)**

The actual value is reset, if there is no signal in Ch-Ainput during this time It can be adjusted from [100001] to [100099]

## Pro-08

#### **Measurement Period**

Number of pulses is counted during this time It can be adjusted from [DDDDD] to [DDDDD9]

## Pro-09

### **Output-1 Function**

10000001

Output-1 is latched. It does not change position until manual reset is applied.

100000 I

Non-latched with hysteresis output is selected.

10000021

Output-1 is an alarm output. For details, refer to Output-1 Alarm functions parameter Pro- 11.



Pro- 10	Output-2 Function
000000	Output-2 is latched. It does not change position until manual reset is applied.
00000 1	Non-latched with hysteresis output is selected.
Pro- ! !	Alarm Functions for Output-1  If Output-1 function parameter Pro-09 is 00000 , Output-1 becomes active according to this parameter
00000	High Alarm.
00000 1	Low Alarm.
000002	Deviation High Alarm.
000003	Deviation Low Alarm.
000004	Deviation Band Alarm.
Pro- 12	Hysteresis for Output-1  Hysteresis for Output-1. It is used if Output-1 is non-latched.  It can be adjusted from ①①①①①② to ②500000
Pro- 13	Hysteresis for Output-2  Hysteresis for Output-2. It is used if Output-2 is non-latched.  It can be adjusted from 000000 to 050000
Pro- 14	Operation form for Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation form for Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 16	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from $\boxed{000000}$ to $\boxed{009999}$ If it is $\boxed{000000}$ , then it operates indefinitely.
Pro- 17	Output-2 Pulse Time
· · ·	Energising time for Output-2. It can be adjusted from [] [] [] [] to [] [] [] If it is [] [] [] [] [] . then it operates indefinitely.



Pro- 18	Start of Controlling
	Controlling is started when the device is energised
	Controlling is started when count value reaches to SET1 value.
000002	Controlling is started when count value reaches to SET2 value.
Pro-20	Point Position for display
000000	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pro-23	Slave Address
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Device address for serial communication bus. It can be adjusted from DDDD I to DDD247
Pro-24	Selection of Modbus Protocol Type
[000000]	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
0	Parity
	No parity
000000	No parity Odd parity
	Odd parity
000002	Odd parity
	Odd parity Even parity
000002 Pro-26	Odd parity Even parity  Baud Rate
000002 Pro-26	Odd parity Even parity  Baud Rate  1200 Baud Rate
000002 Pro-26 000000	Odd parity Even parity  Baud Rate  1200 Baud Rate 2400 Baud Rate
000002 Pro-26 000000 00000 1	Odd parity Even parity  Baud Rate  1200 Baud Rate 2400 Baud Rate 4800 Baud Rate
000002 Pro-26 000000 0000001 0000002	Odd parity Even parity  Baud Rate  1200 Baud Rate 2400 Baud Rate 4800 Baud Rate 9600 Baud Rate
000002 Pro-26 000000 000001 000002 000003	Odd parity Even parity  Baud Rate  1200 Baud Rate 2400 Baud Rate 4800 Baud Rate 9600 Baud Rate 19200 Baud Rate



Pro-28	Reset and Set protection (Accessing from front panel)
000000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	Reset Button, SET1 and SET2 protection is active (Full protection)
000004	SET1 protection is active
000005	SET2 protection is active
Pro-29	Frequency / Cycle Multiplication Coefficient
· · · · · · · · ·	Count value is multiplied with this value. It can be adjusted from DDDD I to
Pro-30	Multiplication Coefficient
<u>, , , , , , , , , , , , , , , , , , , </u>	Count value is multiplied with this value. It can be adjusted from DDDD Ito. 999999. If it is D LDDDD, it has no effect.
	Program Password
	It is used for accessing to the program parameters.
	It can be adjusted from [] [] [] to [] [] 1 [] . If it is [] [] [] [] , there is no password protection.



### 7.8.1 FREQUENCYMETER / TACHOMETER Applications Examples

Two different method are used in Frequencymeter / Tachometer function;

Method -1: To get frequency or cycle value by measuring the revolution time

(This method is used if the sensor sends one pulse per revolution)

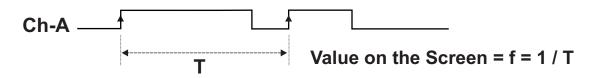
Method -2: To get frequency or cycle value by counting the pulses during the time is set in

Pro-08 parameter

### Method -1:

If <u>Pro-03</u> is 000000;

Measuring starts on rising edge of Ch-Ainput. Time (T) is between two rising edge.



If  $P_{-0}$ -29 parameter is 000001,  $P_{-0}$ -30 parameter is 0.0000, then speed is measured cycle per second.

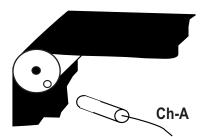
For measuring the speed cycle per minute,  $P_{-0}$  - 29 parameter must be 000060 For measuring the speed cycle per hour,  $P_{-0}$  - 29 parameter must be 003600

### **EXAMPLE-1:**

There is a cloth workbench as shown below:

When  $\boxed{P_{-0}-29}$  parameter is  $\boxed{000000}$ ,  $\boxed{P_{-0}-30}$  parameter is  $\boxed{000000}$ , cloth is advanced 80 cm per revolution and 20 cycle / sec is observed on the display.

User can observe cloth length, 80 cm, on the display by changing the  $P_{-}$  and  $P_{-}$  and  $P_{-}$  and  $P_{-}$ 



If <u>Pro-29</u> =1

Pro-30 Multiplication coefficient = 80/20 = 4

After adjustment of the parameter, 80 cm / sec is observed on the display.

For dm/sec, point position for display parameter  $P_{-0} - 20$  must be 000001 For m/sec, point position for display parameter  $P_{-0} - 20$  must be 000002

For cm / minute,  $P_{-0}$  - 29 parameter must be 00050 For cm / hour,  $P_{-0}$  - 29 parameter must be 003500

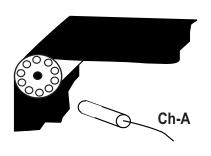


This method must be used if speed is over 100 cycle / second

#### Method -2:

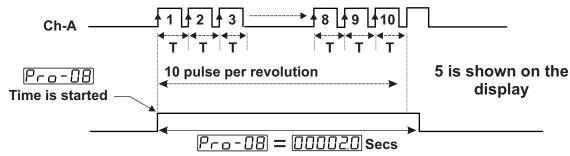
If  $P_{-0}$  - 0.3 parameter is 0.0000 I

Pulses in Ch-A input is counted during time is set in Pro-IB parameter. Average time for one pulse is calculated.



#### **EXAMPLE-2:**

For one revolution of cylinder 10 pulse is applied in Ch-A input during P = 0.00020

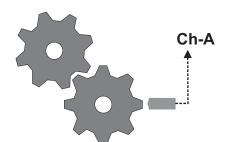


If 10 pulse is applied during 2 secs;

T = 2/10 = 0.2sec f = 1/T f = 5 cycle/sec is shown on the display

If  $P_{-0}$ -29 parameter is 000001 and  $P_{-0}$ -30 parameter is 00000, speed is measured as cycle per second.

For cycle / minute,  $P_{-0}$  - 29 parameter must be 000000 For cycle / hour,  $P_{-0}$  - 29 parameter must be 003600



#### **EXAMPLE-3:**

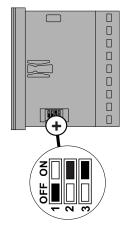
8 pulse is applied per revolution during  $P_{-0}$  - 08 = 000005 If  $P_{-0}$  - 29 parameter is 000001 and

Pro-30 Parameter is [0.1000], speed of the system (cycle per second) is calculated as shown below:

If 8 pulse is applied during 0.5 sec;

T = 0.5/8 = 0.0625sec f = 1/T f = 16 cycle / sec is shown on the display

For cycle / minute,  $P_{CO}$  - 29 parameter must be  $\boxed{000060}$  For cycle / hour,  $P_{CO}$  - 29 parameter must be  $\boxed{003600}$ 



### 7.9 CHRONOMETER Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be changed by time unit and scale selection parameter Pro-05

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be changed by time unit and scale selection parameter  $P_{\Box \Box} = \Box \Box$ 

## Pro-02

### Input Type and Function Selection for Chronometer

Period measurement of signals in Ch-A input

Pulse time measurement of signals in Ch-A input

Sum of the time difference between Ch-A and Ch-B inputs rising edges

## P-o-04

### Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

## P-0-05

### **Time Unit and Scale Selection**

| Hour/Minute

It can be adjusted from 000000 to 009959

☐☐☐☐☐ | Minute / Second

It can be adjusted from  $\square\square\square\square\square\square$  to  $\square\square\square\square\square\square$ 

□□□□□□□ Second/Millisecond

It can be adjusted from 000000 to 009999

□□□□□∃ Hour/Minute

It can be adjusted from  $\square \square \square \square \square \square \square$  to  $\square \square \square \square \square \square \square$ 

□□□□□Ч Hour

It can be adjusted from [00000] to [099999]

Minute

It can be adjusted from [000000] to [099999]

|□□□□□□ Second

It can be adjusted from 000000 to 099999



In operation with Manual or Automatic Reset, at the end of the reset operation, if counting direction parameter  $P_{-} = 19$  is 0 = 0 = 0 (0->P), count value becomes 0 = 0 = 0. If  $P_{-} = 19$  is 0 = 0 = 0 (P->0), count value becomes SET2.



Pco-06	Output Functions
000000	Manual Reset-1. Device continues to count till manual reset is applied. Output-2 pulse time Pro- 17 is not considered.
00000 1	<b>Manual Reset-2.</b> Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time Pro-17 is not considered.
000002	<b>Manual Reset-3.</b> It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.
000003	<b>Automatic Reset-1.</b> Count value becomes zero (for 0->P) when it reaches to SET2 value and device starts to count again.
000004	Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value becomes zero (for 0->P) at the end of output-2 pulse time Pro-17 And device starts to count again.
000005	<b>Automatic Reset-3.</b> Count value becomes zero (for 0->P) when it reaches to SET2 value. Device starts to count again. Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time.
000006	<b>Automatic Reset-4.</b> Counting is continued when count value reaches to SET2 value. Count value becomes zero (0->P)at the end of Output-2 pulse time Pro-17 device starts to count again.
000007	<b>Automatic Reset-5.</b> When count value reaches to SET2 value, SET1 changes position, count value becomes zero (0->P). Output-1 and Output-2 do not change position, until count value reaches to SET2 value.
( ) counti	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is [[[[[]]]]]] (0->P), count value nes [[[]]]]]. If [[[]] - 19] is [[[]]]]] (P->0), count value becomes SET2.
( ) counti	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter
counti becon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is [[[[[]]]]]] (0->P), count value nes [[[]]]]]. If [[[]]-19] is [[[]]]]] (P->0), count value becomes SET2.
counti becon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter \( \bar{P_c \cdot   9} \) is \( D_D_D_D_D_D_D_D_D_D_D_D_D_D_D_D_D_D_D_
counti becon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 000000 (0->P), count value nes 0000000. If Pro-19 is 0000000 (P->0), count value becomes SET2.  Operation form for Output-1  Output-1 Normally non-energised
counti becon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter
countibecon Pro-14  000000  Pro-15	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter
countibecon   Pro- 14   000000   Pro- 15   000000	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 00000 (0->P), count value nes 000000. If Pro-19 is 000000 (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised
countibecon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is [][][][][][][][][][][][][][][][][][][]
countibecon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 000000 (0->P), count value nes 0000000. If Pro-19 is 0000000 (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised
countibecon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 00000 (0->P), count value nes 000000. If Pro-19 is 000000 (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 3 Normally energised Output - 4 Normally energised Output - 5 Normally energised Output - 7 Normally energised Output - 1 Normally energised Output - 2 Normally energised
countibecon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 00000 (0->P), count value nes 000000. If Pro-19 is 00000 (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Pulse Time  Energising time for Output-1. It can be adjusted from 000000 to 009999  If it is 000000, then it operates indefinitely.  Output-2 Pulse Time  Energising time for Output-2. It can be adjusted from 0000000 to 009999
countibecon Pro-14  000000  000000  Pro-15  000000  Pro-15  Pro-17	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is DDDDD (0->P), count value nes DDDDD. If Pro-19 is DDDDD (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised Output - 2 Normally energised Output - 1 Normally energised Output - 1 Normally energised Output - 2 Normally energised Output - 2 Normally energised Output - 1 Normally energised Output - 2 Normally energised If it is DDDDDD to DDBDDDDDDDDDDDDDDDDDDDDDDDDDD
countibecon	ration with Manual or Automatic Reset, at the end of the reset operation, if ing direction parameter Pro-19 is 00000 (0->P), count value nes 000000. If Pro-19 is 000000 (P->0), count value becomes SET2.  Operation form for Output-1  Output - 1 Normally non-energised Output - 1 Normally energised Operation form for Output-2  Output - 2 Normally non-energised Output - 2 Normally energised Output - 1 Pulse Time  Energising time for Output-1. It can be adjusted from 000000 to 009999  If it is 000000 then it operates indefinitely.  Output-2 Pulse Time  Energising time for Output-2. It can be adjusted from 0000000 to 009999  If it is 0000000 then it operates indefinitely.  Selection of counting direction

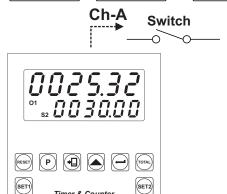
Pro-21	Saving Count Value (Power down back-up)
00000	Count value is saved to memory when power is disconnected and restored on power up.
00000 1	Count value is not saved to memory when power is disconnected
P-0-23	Slave Address
	Device address for serial communication bus. It can be adjusted from DDDDD to DDDZY7
P-0-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
00000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
000000	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
P-0-27	Stop Bit
00000	1 Stop Bit
00000 1	2 Stop Bits
Pro-28	Reset and Set protection (Accessing from front panel)
000000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	Reset Button, SET1 and SET2 protection is active (Full protection)
000004	SET1 protection is active
000005	SET2 protection is active
P-0-P5	Program Password
	It is used for accessing to the program parameters. It can be adjusted from $\boxed{000000}$ to $\boxed{009999}$ . If it is $\boxed{000000}$ , there is no password protection.

### 7.9.1 Examples About CHRONOMETER Applications

### **EXAMPLE-1:**

There is a switch for giving start and stop signal on Ch-Ainput.

Pro-02 = 000001; Pro-04 = 000050; Pro-05 = 000001 iken;



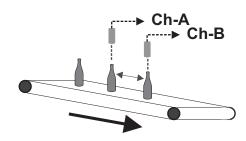
When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.

Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

### **EXAMPLE-2:**

There is a production band as shown below. There are two sensors, first is on Ch-A input used for starting the system, second is on Ch-B input used for stopping the system. If

$$P_{-0}-02 = 000002$$
;  $P_{-0}-04 = 000050$ ;  $P_{-0}-05 = 000001$ ;



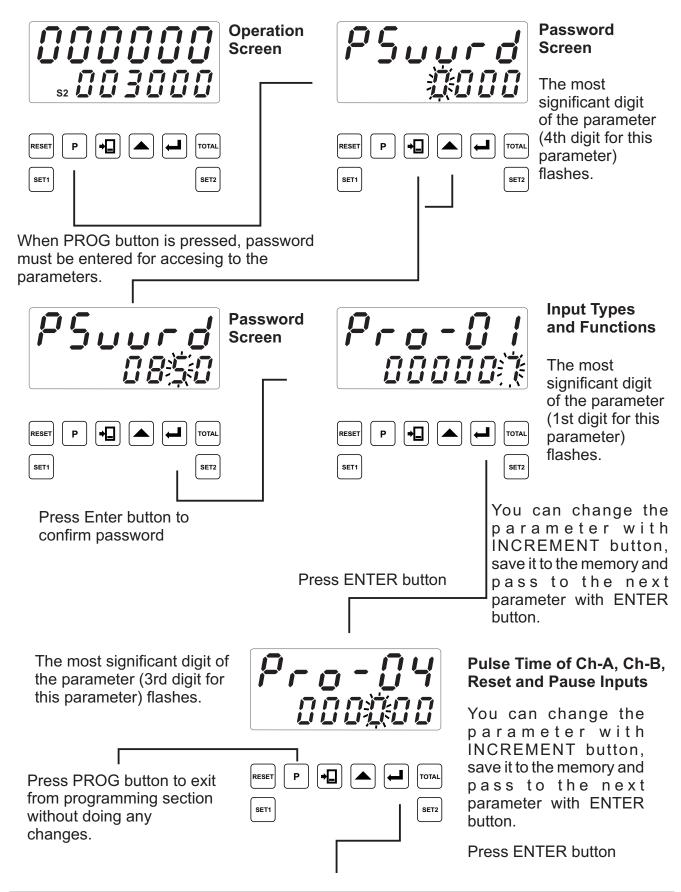
When the object passes in front of the first sensor on Ch-A input, counting is started (Minute / second).

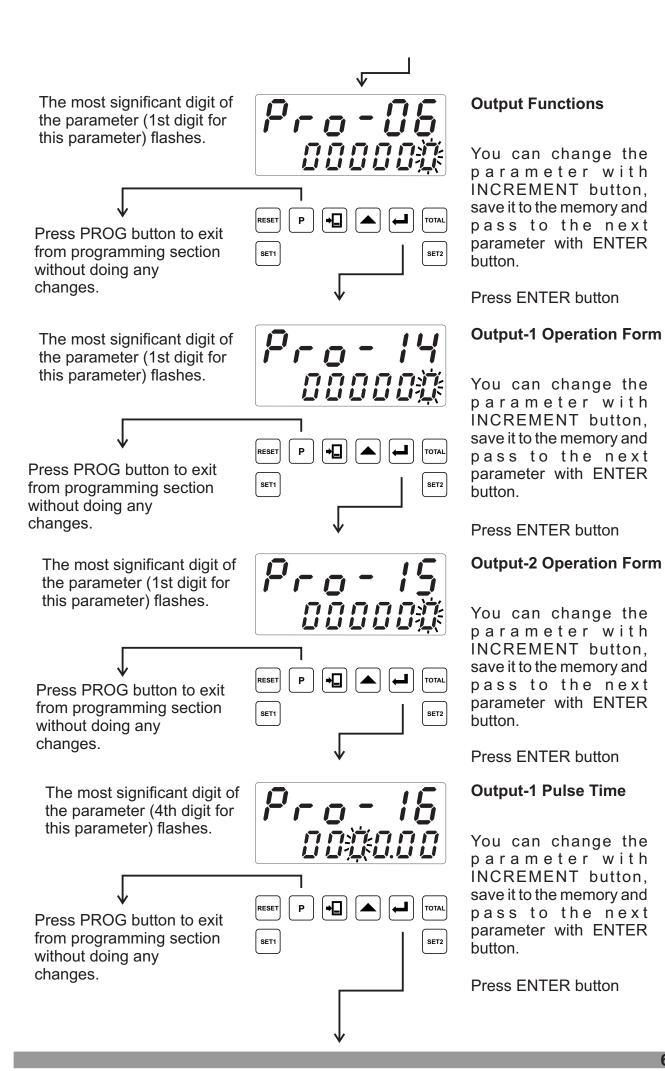
When the object passes in front of the second sensor on Ch-B input, counting is stopped.

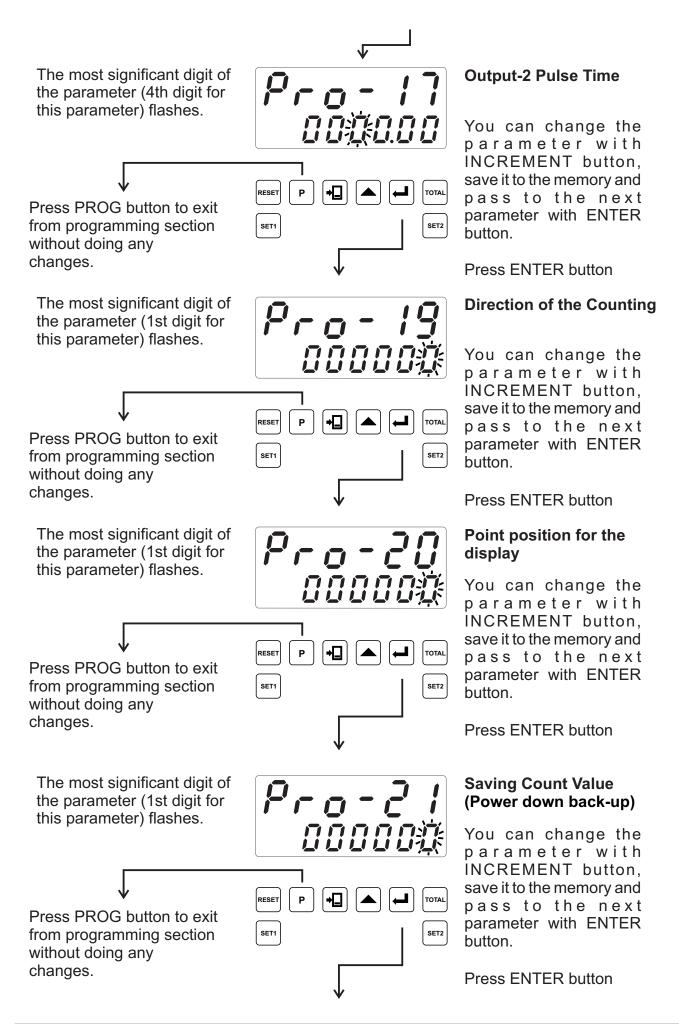
Time between two objects can be determined.

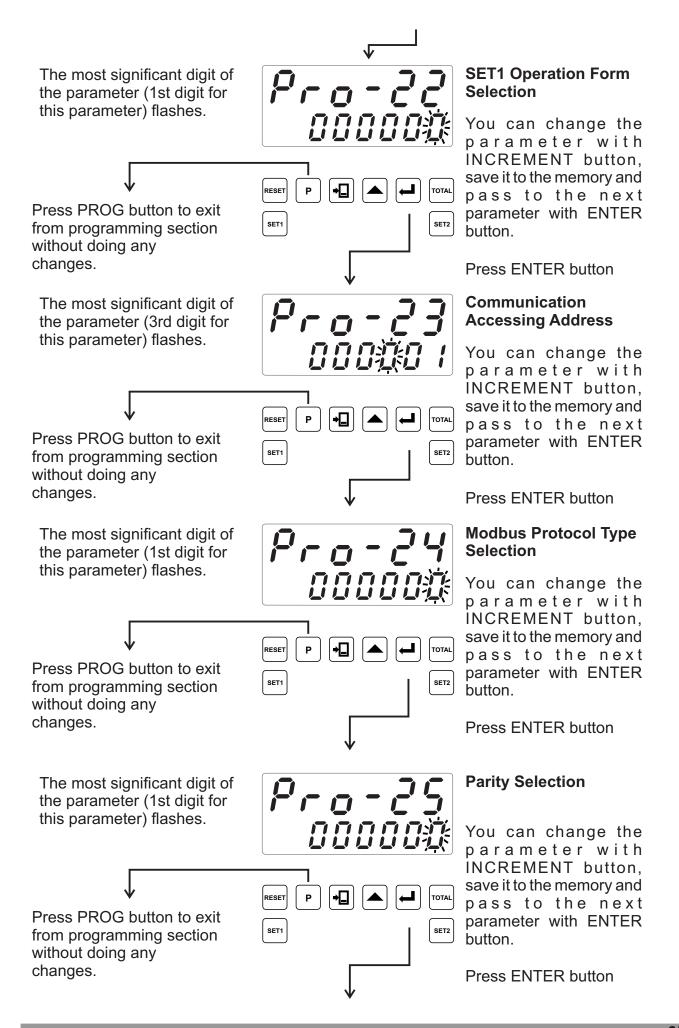
### 7.10 Accessing to the Program Parameters

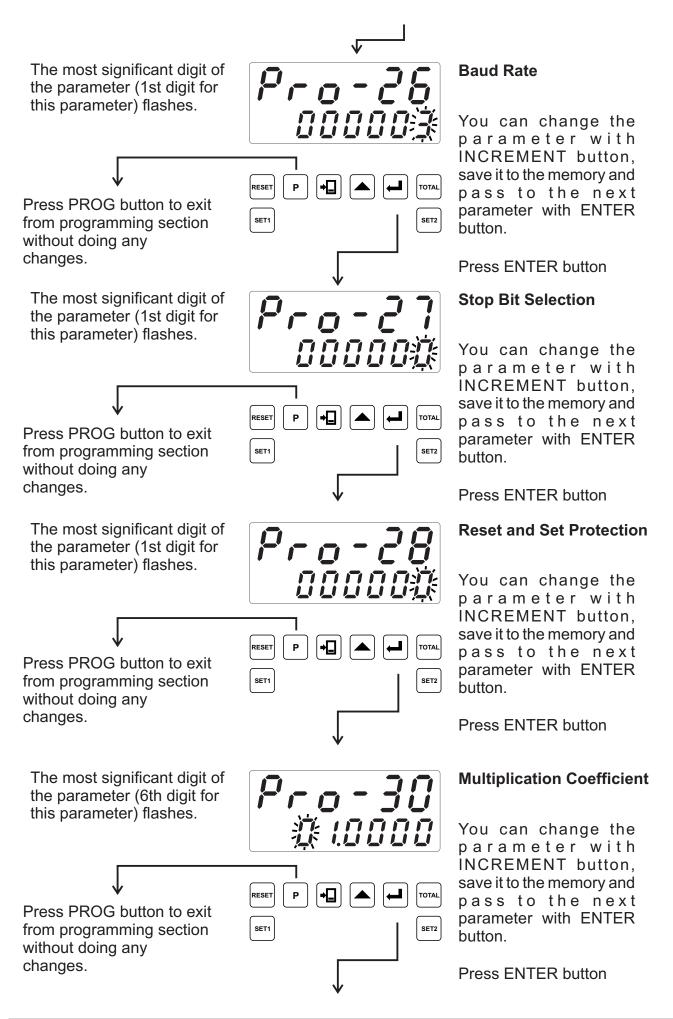
Parameters are grouped as program parameters. Accessing to the program parameters is same for all functions. So, only accessing to the program parameters for COUNTER / "TOTALIZER COUNTER" is explained in this section. For details on parameters refer to PROGRAM PARAMETERS section.

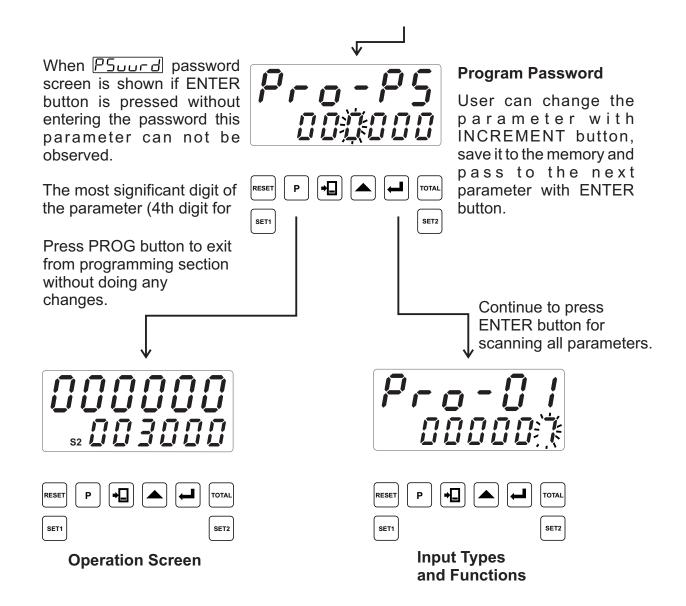












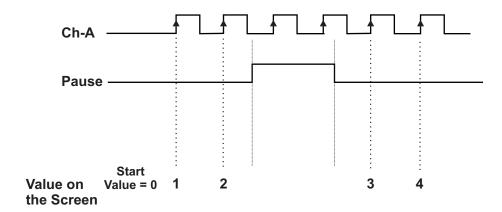
### 8. Program Parameters



Input Types and Functions (It is accessible in COUNTER / "TOTALIZER COUNTER" and BATCH COUNTER functions)

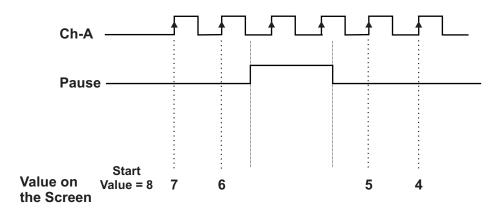


Upcount on rising edge of Ch-Ainput



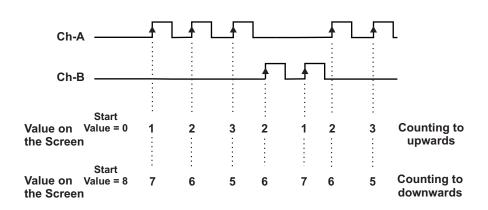


Downcount on rising edge of Ch-Ainput.



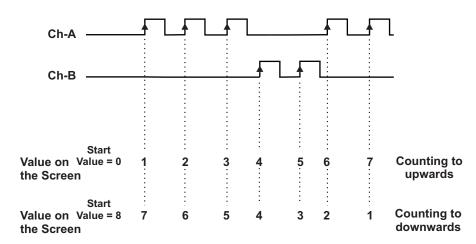


Upcount on rising edge of Ch-Ainput. Downcount on rising edge of Ch-Binput.



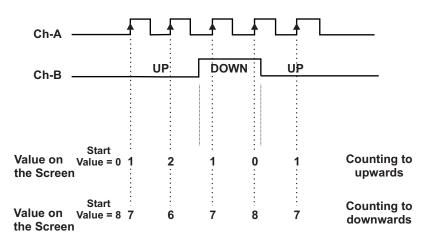
## 000003

Upcount on rising edge of Ch-Ainput Upcount on rising edge of Ch-Binput



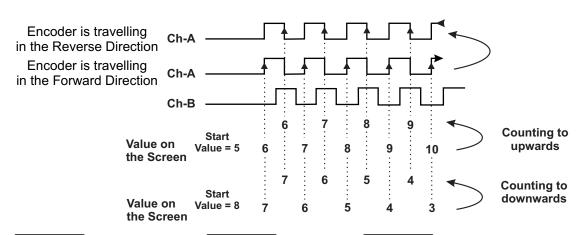
# 000004

Upcount on rising edge of Ch-Ainput when Ch-B is at 0 Downcount on rising edge of Ch-Awhen Ch-B is at 1



# 000005

x1 Phase Shifting (for incremental encoders) Upcount on rising edge of Ch-A input when Ch-B is at 0 Downcount on rising edge of Ch-A input when Ch-B is at 1



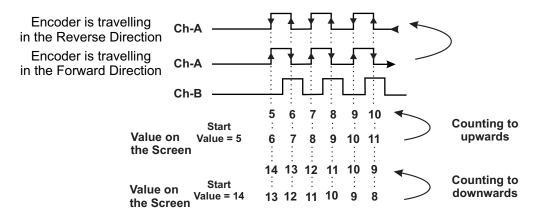


If Pro-01 is 000005, Pro-04 must be 00000. If not counting is not performed.



**x2 Phase Shifting** (for incremental encoders) Upcount on rising edge of Ch-A when Ch-B is at 0 Downcount on rising edge of Ch-A when Ch-B is at 1

Upcount on falling edge of Ch-Awhen Ch-B is at 1 Downcount on falling edge of Ch-Awhen Ch-B is at 0





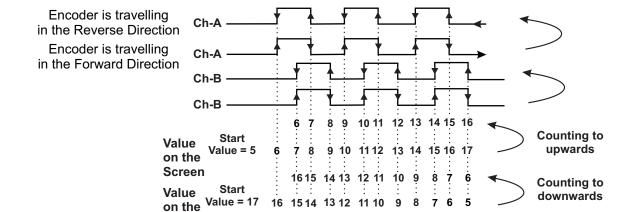
If Pro-01 is 000006, Pro-04 must be 000000 .If not counting is not performed.



Screen

**x4 Phase Shifting** (for incremental encoders)
Upcount on rising edge of Ch-A when Ch-B is at 0
Downcount on falling edge of Ch-A when Ch-B is at 0
Downcount on rising edge of Ch-A when Ch-B is at 1
Upcount on falling edge of Ch-A when Ch-B is at 1

Downcount on rising edge of Ch-B when Ch-A is at 0 Upcount on falling edge of Ch-B when Ch-A is at 0 Upcount on rising edge of Ch-B when Ch-A is at 1 Downcount on falling edge of Ch-B when Ch-A is at 1





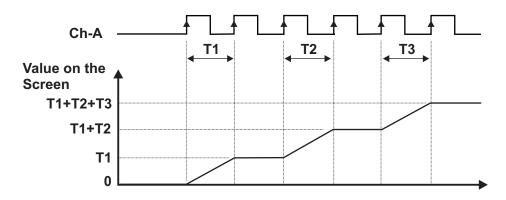
If  $P_{-a}$  is  $\boxed{00000}$ ,  $\boxed{9}$ ,  $\boxed{9}$  must be  $\boxed{000000}$ . If not counting is not performed.



Selection of Input Type Function for Chronometer (It is accessible only in CHRONOMETER function)

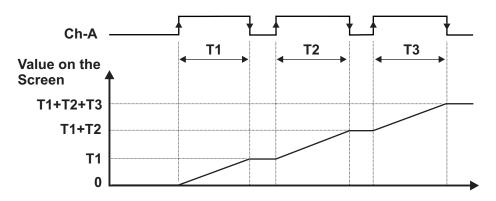
000000

Period measurement in Ch-Ainput.



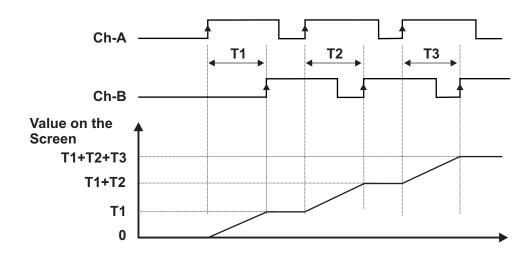
00000 1

Pulse time measurement in Ch-Ainput.



000002

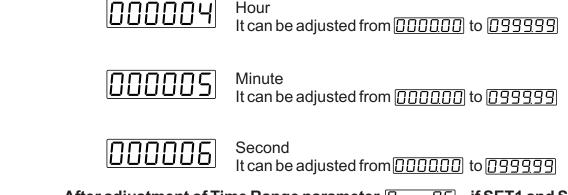
Sum of the time difference between Ch-A and Ch-B inputs rising edges



(i)

Input type function selection parameter  $\boxed{P - o - \Box 2}$  for chronometer is performed according to the time range is set in Time Unit and Scale selection parameter  $\boxed{P - o - \Box S}$ 

Selection of Measuring Method (It is accessible only in FREQUENCYMETER / TACHOMETER Function)	
000000	Frequency or cycle is calculated by measuring cycle time of the signals in Ch-Ainput
00000 1	Frequency or cycle is calculated by counting the pulses in Ch-A input during the time is set in measurement period parameter Pro-08
For details on these methods, refer to Section 7.8.1"Examples About Frequencymeter/Tachometer Function Applications" Only Ch-A input performs in Frequencymeter / Tachometer function.	
Pulse Time of Ch-A, Ch-B, Reset and Pause Input (It is accessible in functions except for TIMER function)	
less than the de It can be adjuste @@@@@@then	ect against the electrical contact debounce or the signal that is termined pulse time. ed from [][][][][][][][][][][][][][][][][][][]
If Input Types and Functions parameter Pro-01 is 000005, 000005 or 000000 then pulse time of Ch-A and Ch-B parameter Pro-04 must be 0000000. If not counting is not performed.	
Selection of Time Unit and Scale (It is accessible in TIMER and CHRONOMETER functions)	
000000	Hour / Minute It can be adjusted from \$\oldsymbol{D} \oldsymbol{D} \olds
00000 1	Minute / Second It can be adjusted from [] [] [] [] to [] [] [] [] [] [] [] [] [] [] [] [] []
000002	Second / Millisecond It can be adjusted from [] [] [] [] to [] [] [] [] [] []
000003	Hour / Minute It can be adjusted from [] [] [] [] to [] [] 2 3 5 9





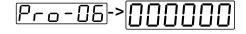
After adjustment of Time Range parameter  $P_{CO} - P_{CO}$ , if SET1 and SET2 values are not appropriate for this selection, SET1 and SET2 are changed according to this selection. (E.g. If time range is 99.99 and SET1 is 45.94, there is no problem. If time range is 99.59 and SET1 is 45.94, then SET1 is changed as 45.59)



**Output Functions** 

(It is accessible in functions except for FREQUENCYMETER / TACHOMETER function)

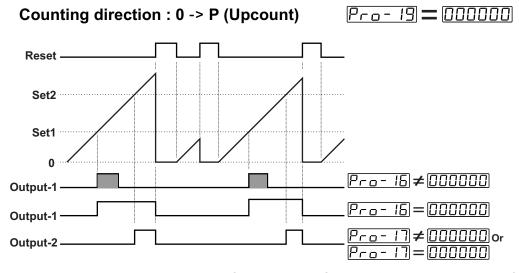
This parameter can be adjusted from [20000] to [2000] in Batch Counter function and operates different from the other functions.



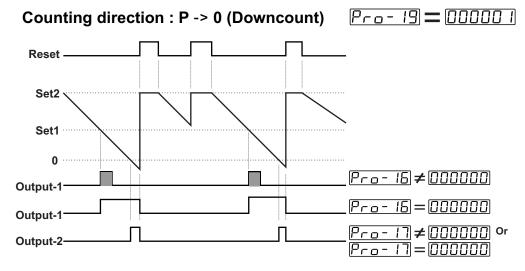
Manual Reset-1.

Device continues to count till manual reset is applied. Output-2 pulse time  $\boxed{\frac{P_{ro} - 1}{1}}$  is not considered.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

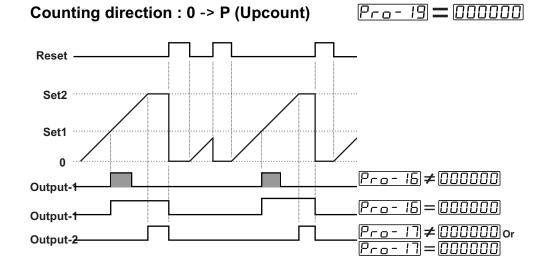


Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.



Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:



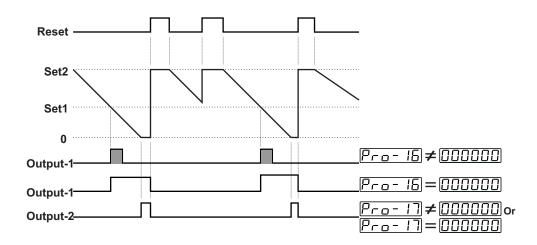
When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time  $\boxed{P_{ \square} - I_{\square}}$  is  $\boxed{00000000}$ , Output-1 does not change position until manual reset input is active. If Output-1 pulse time  $\boxed{P_{ \square} - I_{\square}}$  is not 0, Output-1 becomes inactive at the end of the pulse time.

When the count value reaches to SET2 value, Output-2 becomes active. Counting does not continue over SET2 value. For starting to count manual reset input must be active. Output-2 Pulse Time  $\boxed{P_{\Gamma \square} - I ?}$  Is not considered.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

# How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

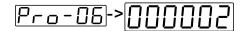
Counting direction : P -> 0 (Downcount)



When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time  $\boxed{P_{ \square } - I_{\square}}$  is  $\boxed{0000000}$ , Output-1 does not change condition until manual reset input is active. If Output-1 pulse time  $\boxed{P_{ \square } - I_{\square}}$  is not 0, Output-1 becomes inactive at the end of the pulse time.

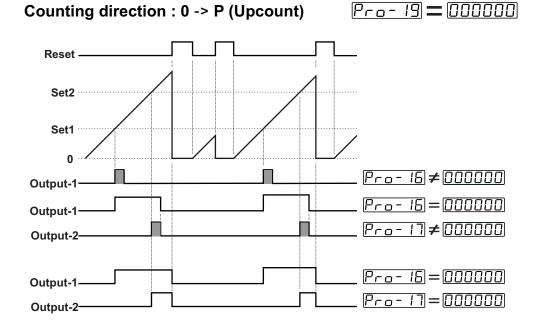
When the count value reaches to DDDDDD value, Output-2 becomes active. Counting does not continue under DDDDDD . For starting to count manual reset input must be active. Output-2 pulse time Pro-!?

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.



Manual Reset-3.
Counting continues until Manual Reset input is active.
(Output-2 Pulse Time Pro-17 is considered)

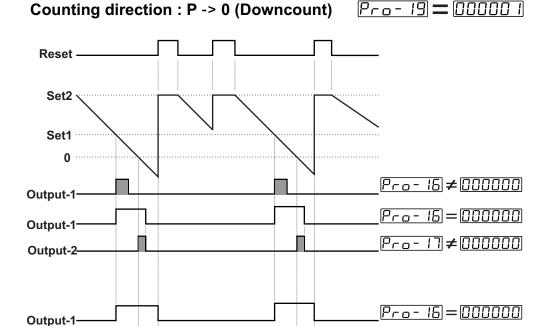
How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:



When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 Pulse Time  $P_{-D} - I_{\overline{D}}$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $P_{-D} - I_{\overline{D}}$  is DDDDD changes position until Manual Reset input is active or according to Output-2.

When the count value reaches to SET2 value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse Time Pro-17 is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.



When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time  $Pr_{-}-I_{-}$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $Pr_{-}-I_{-}$  is  $Output_{-}$  it changes position until Manual Reset input is active or according to Output-2.

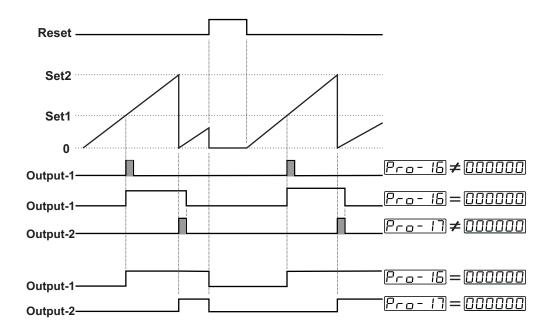
Output-2-

When count value reaches to [][][][][] value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse time [Pro-17] is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

Pro- 17 = 000000





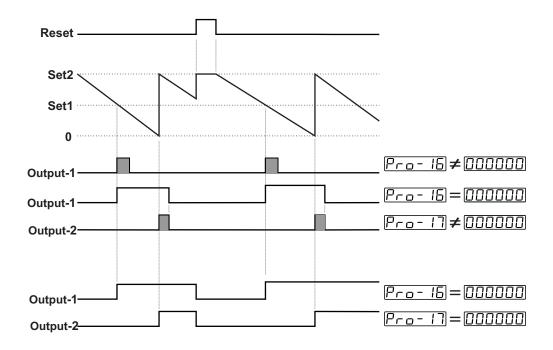
When the count value reaches to SET2 value, Output-2 becomes active. Count value is reset. If Output-2 pulse time Pro-17 is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.



If output functions parameter Pro-05 is selected Automatic Reset ( 000003 000004, 000005 or 000005, then Pro-17 must be different from zero. If not Automatic Reset is not realised.

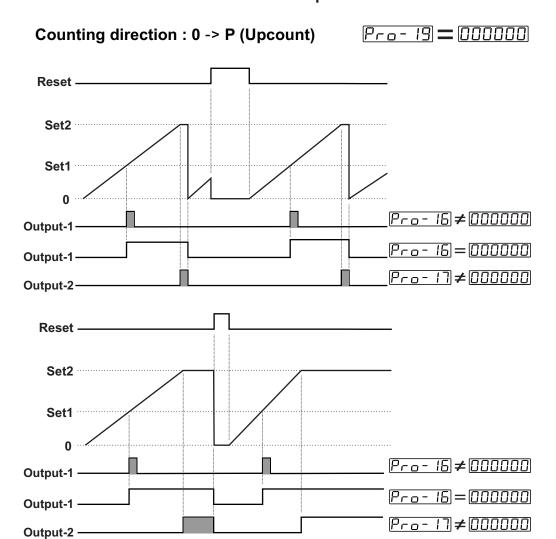
Counting Direction : P -> 0 (Downcount)



When the count value reaches to [][][][][] value, Output-2 becomes active. Count value becomes equal to Set-2 value and counting is started again. If Output-2 pulse time [Pro-17] is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.





When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time  $P_{\neg \neg \neg} = I_{\Box}$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $P_{\neg \neg \neg} = I_{\Box}$  is  $\Box \Box \Box \Box \Box \Box \Box$ , it changes position until Manual Reset input is active or according to Output-2 position.

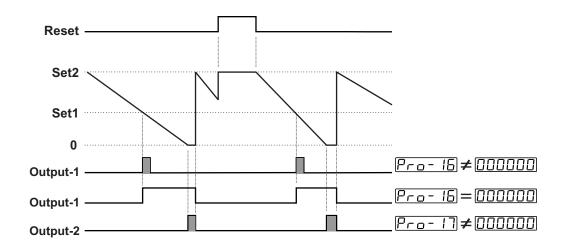
When the count value reaches to SET2, Output-2 becomes active. Counting is stopped. If Output-2 pulse time Pro-17 is not 0, count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

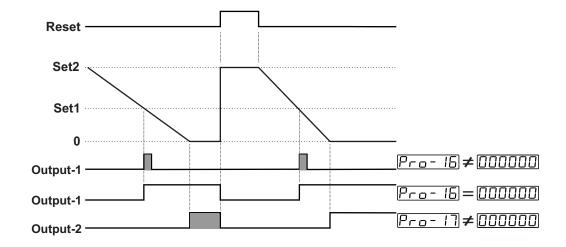
Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.



If output functions parameter Pro-05 is selected Automatic Reset (000003 000004,00005 or 000005, then Pro-17 must be different from zero. If not, Automatic Reset is not realised.

Counting direction:  $P \rightarrow 0$  (Downcount)  $P - 0 \rightarrow 19 = 0000000000$ 





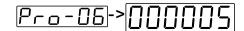
When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time  $P_{-D} - IB$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $P_{-D} - IB$  is Output-1 pulse time is active or according to Output-2 position.

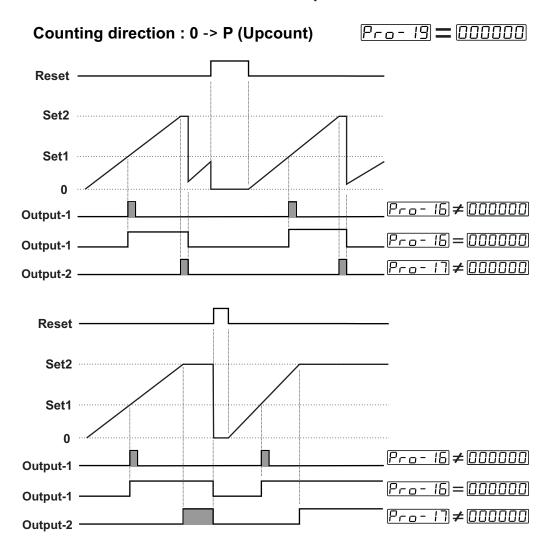
When the count value reaches to  $\boxed{\square \square \square \square \square}$  value, Output-2 becomes active. Counting is stopped. If Output-2 pulse time  $\boxed{P_{ \square \square} - I \rceil}$  is not 0, count value becomes equal to SET2 value, counting is started again and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER /" TOTALIZER COUNTER" functions.



If output functions parameter  $P_{-a} - 06$  is selected Automatic Reset ( 000003 000004, 000005 or 000006, then  $P_{-a} - 17$  must be different from zero. If not, Automatic Reset is not realised.





When the count value reaches to SET1, Output-1 becomes active.If Output-1 pulse time  $P_{\neg \Box} - I_{\Box}$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $P_{\neg \Box} - I_{\Box}$  is  $\boxed{000000}$ , it changes position until Manual Reset input is active or according to Output-2 position.

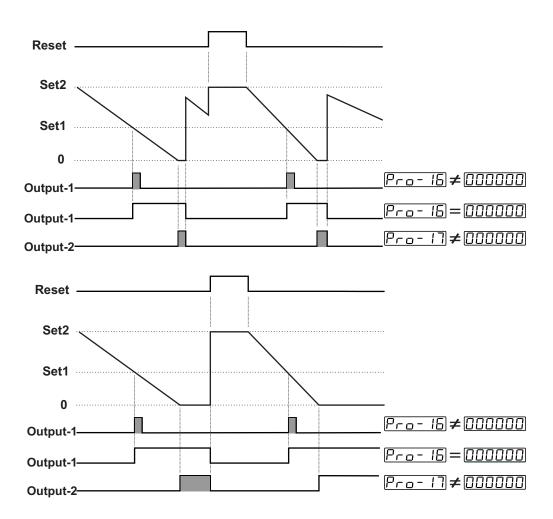
When the count value reaches to SET2, Output-2 becomes active and count value is reset.

When the count value reaches to SET2, Output-2 becomes active and count value is reset. But SET2 value is observed in actual value display. If Output-2 pulse time Pro-17 is not 0, count value is observed in actual value display and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER/ "TOTALIZER COUNTER" functions.



Counting Direction: P -> 0 (Downcount) Pro- 19 = 000001



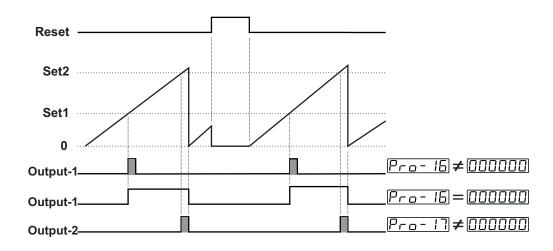
When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pro-Ib is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time Pro-Ib is Output-1 is Output-1 is changes position until Manual Reset input is active or according to Output-2 position.

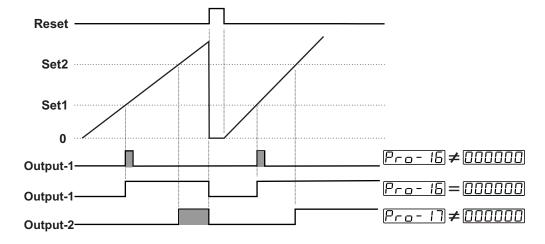
Count value is added to total count value when automatic reset is active in COUNTER/" TOTALIZER COUNTER" functions.



If output functions parameter Pro-05 is selected Automatic Reset (000003 000004,00005 or 000005, then Pro-17 must be different from zero. If not, Automatic Reset is not realised.

Counting direction : 0 -> P (Upcount)





When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time  $P_{\neg \Box} - I_{\Box}$  is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time  $P_{\neg \Box} - I_{\Box}$  is  $P_{\neg \Box} - P_{\Box}$ , it changes position until Manual Reset input is active or according to Output-2 position.

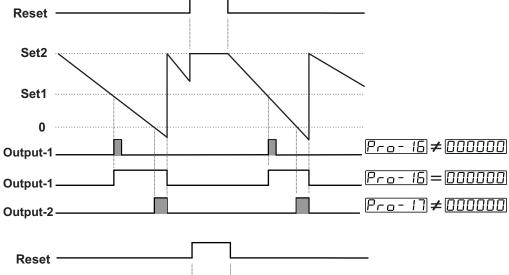
When the count value reaches to SET2, Output-2 becomes active and counting continues over 0. If Output-2 pulse time Pro-17 is not 0, count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

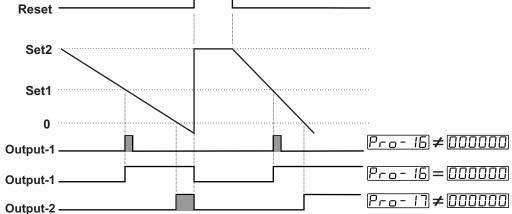
Count value is added to total count value when automatic reset is active in COUNTER/ "TOTALIZER COUNTER" functions.



If output functions parameter Pro-05 is selected Automatic Reset (000003 000004,00005 or 000005, then Pro-17 must be different from zero. If not, Automatic Reset is not realised.

Counting Direction: P -> 0 (Downcount)

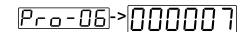




When count value reaches to DDDDD value, Output-2 becomes active and counting continues under 0. If Output-2 pulse Pro-17 time is not 0, count value becomes equal to SET2 and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

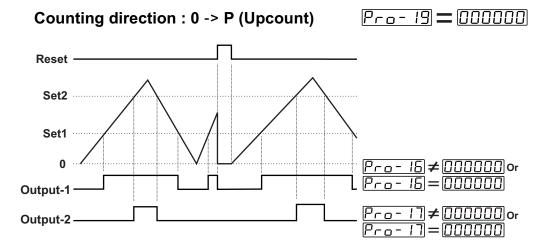




**Automatic Reset-5** 

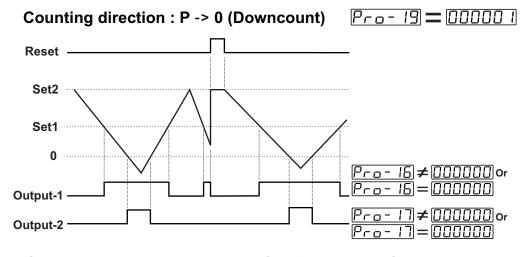
Pulse times  $P_{-0}$  - 15 and  $P_{-0}$  - 17 is not considered.

How it operates in COUNTER / "TOTALIZER COUNTER" functions are explained below:



If count value is equal or greater than SET1 value, then Output-1 becomes active. Output-1 pulse time  $P_{\neg \Box} - I_{\Box}$  is not considered. If count value is equal or greater than SET2 value, then Output-2 becomes active. If count value is less than SET2 value, Output-2 becomes inactive. Output-2 pulse time  $P_{\neg \Box} - I_{\Box}$  is not considered.

Count value is added to total count value when Manual Reset is performed.

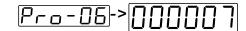


If count value is equal or less than SET1 value, then Output-1 becomes active. If it is greater than SET1 value, Output-1 becomes inactive. Output-1 pulse time Pro-15 is not considered.

Count value is added to total count value when Manual Reset is performed.



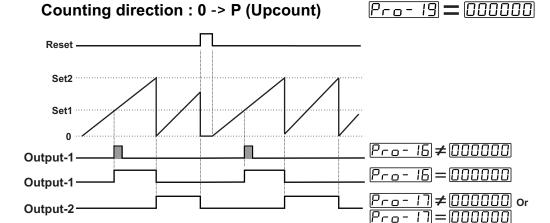
It is preferred if upcount and downcount is performed at the same time.



Automatic Reset-5

Output-2 Pulse Time Pro- 17 is not considered

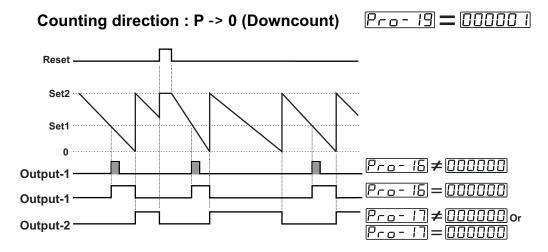
How it operates in TIMER and CHRONOMETER functions are explained below:



If count value is equal to or greater than SET1 value, then Output-1 becomes active. If Output-1 pulse time Pro-IB is not 0, Output-1 changes position at the end of the pulse time. If Output-1 pulse time Pro-IB Is ISIDDDDD, then Output-1 becomes inactive when count value reaches to SET2 value.

When count value reaches to SET2 value, count value is reset and Output-2 becomes active. Output-2 does not change position until count value reaches to SET2 value again.

Output-2 pulse time Pro- 17 is not considered.

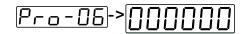


Output-1 becomes inactive.

When count value reaches to  $\boxed{000000}$ , count value becomes equal to SET2 value and Output-2 becomes active. Output-2 does not change position until count value reaches to  $\boxed{000000}$  again. Output-2 pulse time  $\boxed{9 - a - 17}$  Is not considered.

# Pro-05

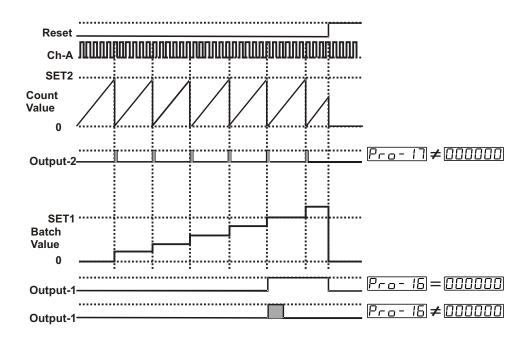
### **Output Functions for BATCH COUNTER**



**Manual Reset** 

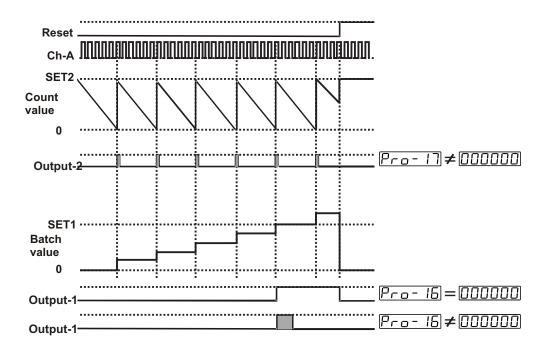
How it operates in BATCH COUNTER function is explained below:

Counting direction : 0 -> P (Counting to upwards)



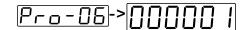
When count value reaches to SET2 value, count value is reset and Output-2 becomes active. If Output-2 pulse time  $\boxed{Pro-17}$  is  $\boxed{000000}$  Then Output-2 does not change position until manual reset input is active. If Output-2 pulse time  $\boxed{Pro-17}$  is not 0, Output-2 becomes inactive at the end of the pulse time.

#### How it operates in BATCH COUNTER function is explained below:



When count value reaches to  $\square \square \square \square \square \square \square \square \square \square$ , count value becomes equal to SET2 and Output-2 becomes active. If Output-2 Pulse Time  $\boxed{Pr_{\square} - 1 ?}$  is  $\boxed{\square \square \square \square \square \square \square}$ , then Output-2 does not change position until manual reset input is active. If Output-2 pulse time  $\boxed{Pr_{\square} - 1 ?}$  is not 0, then Output-2 becomes inactive at the end of the pulse time.

When Output-2 becomes active, batch count value is added 1(Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET-1 value, then Output-1 becomes active. If Output-1 pulse time  $\boxed{Pra-16}$  is  $\boxed{000000}$ , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time  $\boxed{Pra-16}$  is not, then Output-1 becomes inactive at the end of the pulse time.

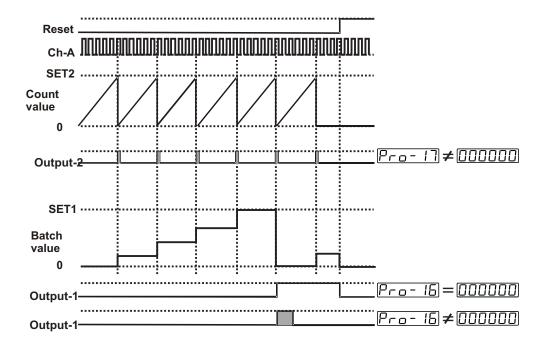


#### **Automatic Reset**

How it operates in BATCH COUNTER function is explained below:

Counting direction : 0 -> P (Upcount)

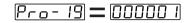


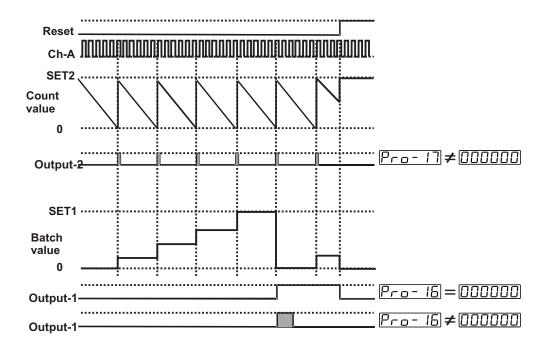


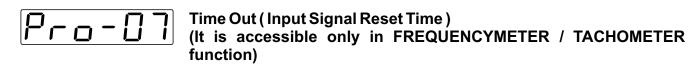
When count value reaches to SET2 value, count value is reset and Output-2 becomes active. If Output-2 pulse time  $\boxed{Pro-17}$  is  $\boxed{0000000}$  Then Output-2 does not change position until manual reset input is active. If Output-2 pulse time  $\boxed{Pro-17}$  is not 0, Output-2 becomes inactive at the end of the pulse time.

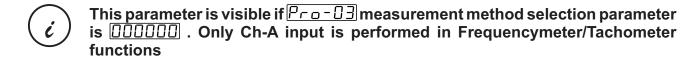
When Output-2 becomes active, 1 is added to batch count value is (Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET1 value, then Output-1 becomes active and Batch count value is reset automatically. If Output-1 pulse time  $P_{ro} - I_{b}$  is  $Output_{b} - I_{b}$ , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time  $P_{ro} - I_{b}$  is not 0, then Output-1 becomes inactive at the end of the pulse time.

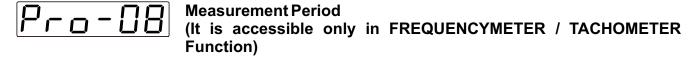
#### Count direction : P -> 0 (Downcount)

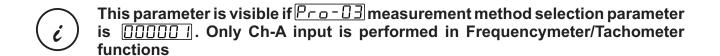


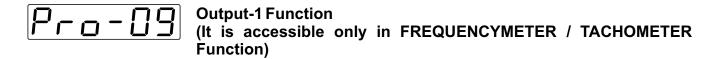






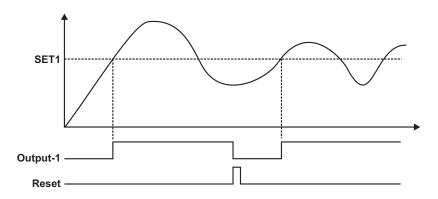






Output is latched. Output-1 does not change position until Manual reset is applied.

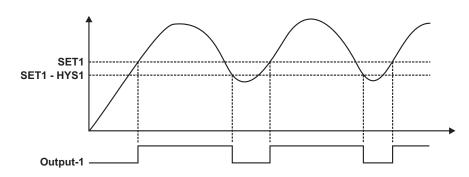
#### Output-1 is latched





Non-latched with hysteresis output is selected.

### Output-1 is non-latched

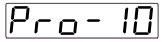


000002

Output-1 is an alarm output. For details, refer to Alarm Functions for Output-1 parameter  $P_{\neg \neg} = II$ 



Only Ch-A input is performed in Frequencymeter/Tachometer functions

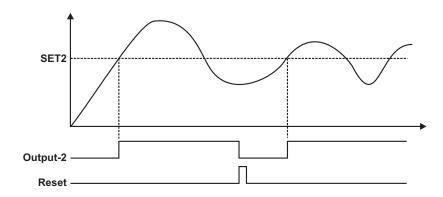


Output-2 Function (It is accessible only in FREQUENCYMETER / TACHOMETER Function)



Output is latched. Output-2 does not change position until Manual reset is applied.

#### **Output-2 is latched**

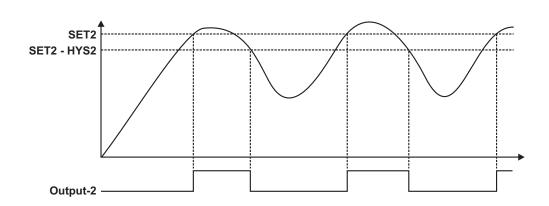




 ${\bf Only\,Ch-A\,input\,performs\,in\,Frequency meter\,/\,Tachometer\,function}.$ 

Non-latched with hysteresis output is selected.

### Output-2 is non-latched



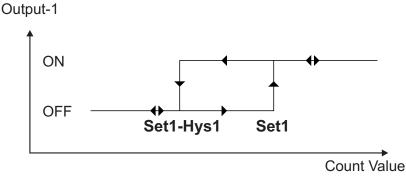
Only Ch-A input is performed in Frequencymeter/Tachometer functions

Alarm Functions for Output-1 (It is accessible only in FREQUENCYMETER / TACHOMETER Function)

If Output-1 function parameter Pro-09 is selected 000002 Alarm output, then Output-1 becomes active according to this parameter.

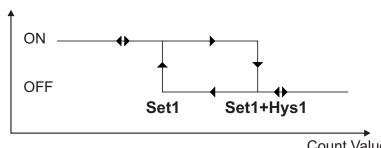
000000

High Alarm.



Low Alarm.



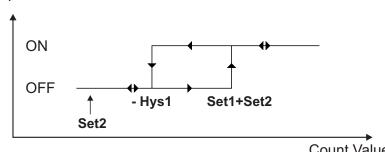


Count Value

Only Ch-A input performs in Frequencymeter / Tachometer function.

**Deviation High Alarm.** 

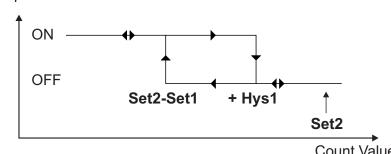




Count Value

**Deviation Low Alarm.** 

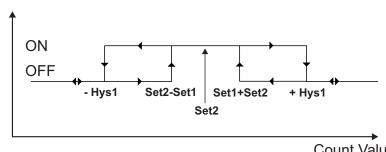
### Output-1



Count Value

**Deviation Band Alarm.** 

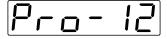
#### Output-1



Count Value



Only Ch-Ainput performs in Frequencymeter / Tachometer function.



**Hysteresis for Output-1** (It is accessible in FREQUENCYMETER / TACHOMETER functions)

It defines hysteresis for Output-1. It is used if Output-1 is non-latched. It can be adjusted from [][][][][][] to [][50000]



Only Ch-A input performs in Frequencymeter / Tachometer function.

Pro- 13	Hysteresis for Output-2 (It is visible only in FREQUENCYMETER / TACHOMETER Function)
	It defines hysteresis for Output-2. It is used if Output-2 is non-latched. It can be adjusted from [][][][][][][][][][][][][][][][][][][]
Only Ch-Air	nput performs in Frequencymeter / Tachometer function.
Pro- 14	Output-1 Operation Form
000	Output-1 Normally non-energised
000	Output-1 Normally energised
Pro- 15	Output-2 Operation Form
000	Output-2 Normally non-energised
000	Output-2 Normally energised
Pro- 15	Output-1 Pulse Time  It determines how long Output-1 will be active.  It can be adjusted from 0000.00 to 0099.99 seconds.  If it is 0000.00 second, then it operates indefinitely.  For details, refer to the section where output functions Pro-Ds are defined
Pro- 17	Output-2 Pulse Time  It determines how long Output-2 will be active. It can be adjusted from 0000.00 to 0099.99 seconds. If it is 0000.00 second, then it operates indefinitely. For details, refer to the section where output functions Pro- are defined
Pro- 18	Start of the Controlling (It is accessible only in FREQUENCYMETER/TACHOMETER functions)
	Outputs are controlled according to this parameter
000	Control is started when the unit is energised.
000	Control is started when count value reaches to SET1 value
000	Control is started when count value reaches to SET2 value.

<u>「「□                                   </u>	of Counting cessible in functions except for ETER functions)	or FREQUENCYMETER
000000	Upcount. (0 -> Preset)	
00000 1	Downcount. ( Preset -> 0 )	
	nctions parameter Pro-II is IZER COUNTER" functions, the can not be accessed.	
<b>アドロービビ</b> (It is ad	ition for Display ccessible in functions ex METER functions)	cept for TIMER and
00000	No point	000000
00000 !	Between first and second digits	00000.0
000002	Between second and third digits	0000.00
000003	Between third and fourth digits	000.000
000004	Between fourth and fifth digits	00.0000
[ [ It is acc	ount Value (Power down back-up cessible in functions except for ETER functions)	
000000	Count value is saved to m disconnected and restored on pover	
00000 1	Count value is not saved to	

screen.

	eration Form Selection cessible only in COUNTER / "TOTALIZER COUNTER"
Function	
000000	Absolute operation.SET1 can be adjusted from $\boxed{000000}$ to $\boxed{999998}$
00000	Operation with offset. SET1 can be defined ± Offset according to SET2 value.(SET1 = SET1 + SET2)
	For example ;if operation with offset is selected, SET1 = 5000, SET2 = 10000.  Output-1 becomes active or inactive according to SET1 = 5000 + 10000 = 15000 value
	For example; If operation with offset is selected; If 6th digit of the SET1 is adjusted to "-", SET1 becomes negative (For details, refer to Section 7.3) SET1 = -05000; SET2 = 10000 Output-1 becomes active or inactive according to SET1 = -5000+10000 = 5000 value
Slave Ad	dress
	dress for serial communication bus. djusted from [][][][][] to [][][][][][]
Pro-24 Modbus	Protocol Type Selection
000000	Modbus <b>ASCII</b> protocol is selected
00000 1	Modbus RTU protocol is selected
Pro-25 Commun	ication Parity Selection
000000	No parity
00000 1	Odd Parity

Even Parity

Pro-25 Baud Rate	e
000000	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
Pro-27 Communi	cation Stop Bit selection
000000	1 Stop Bit
00000 1	2 Stop Bits
Reset and	Set protection (For accessing from front panle)
000000	There is no Reset and Set protection
00000 1	Only RESET button protection is active. Actual value can not be reset by Reset button. Actual value can be reset only reset input is active
000002	SET1 and SET2 can not be changed.
000003	Full protection; Reset protection is active, also SET1 and SET2 can not be changed.
000004	SET1 can not be changed.
000005	SET2 can not be changed.
	y/CycleCoefficient essible only in FREQUENCYMETER / TACHOMETER )

It can be adjusted from [] [] [] to [] [] Count value is multiplied

with this parameter.

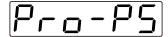
If it is [[] [] [] [] multiplication is not performed. So number of pulses are displayed without having any changes.

尸	_	$\overline{}$	_	$\overline{\exists}$	$\overline{\Pi}$
	ı	<u></u>			<u> </u>

## Multiplication Coefficient (It is accessible except for TIMER and CHRONOMETER functions)

It can be adjusted from  $\boxed{000000}$  to  $\boxed{999999}$ . Changes in this parameter is evaluated when counting starts.

If it is \( \begin{align\*} \ldots \ldots \\ \dots \\ \dot



#### **Program Password**

It is used for accessing to the program parameters. It can be adjusted from [00000] to [009999].

If it is \( \overline{\text{DDDDDD}} \), there is no password protection while accessing to the parameters.

When programming button is pressed, ProL will appear on the display.

If program password is not "0" while accessing to the program parameters:

**1-** If user does not enter the PSuurd value correctly; operation screen will appear without entering to operator parameters.

**2-**When **PSourd** in top display and **DDDDD** in bottom display, if user presses ENTER button without entering password (for observing the parameters):

User can see all parameters except Program Password but device does not allow to do any changes with parameters.

( Please refer to Section 9. Failure Messages in mL-MFU6 Programmable Timer & Counter (2))

## 9. Failure Messages in mL-MFU6 Programmable Timer & Counter



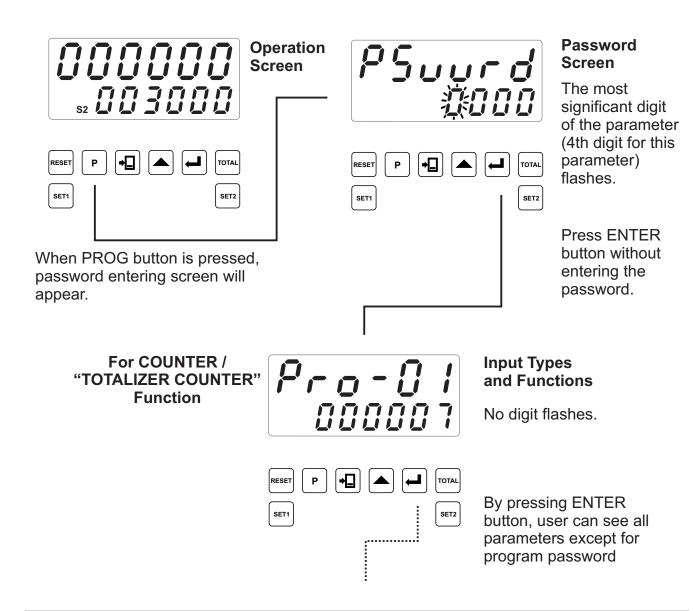
**1 -** Position of the DIP Switch is wrong. (DIP Switch determines the operation function of the device and it is under the top cover)

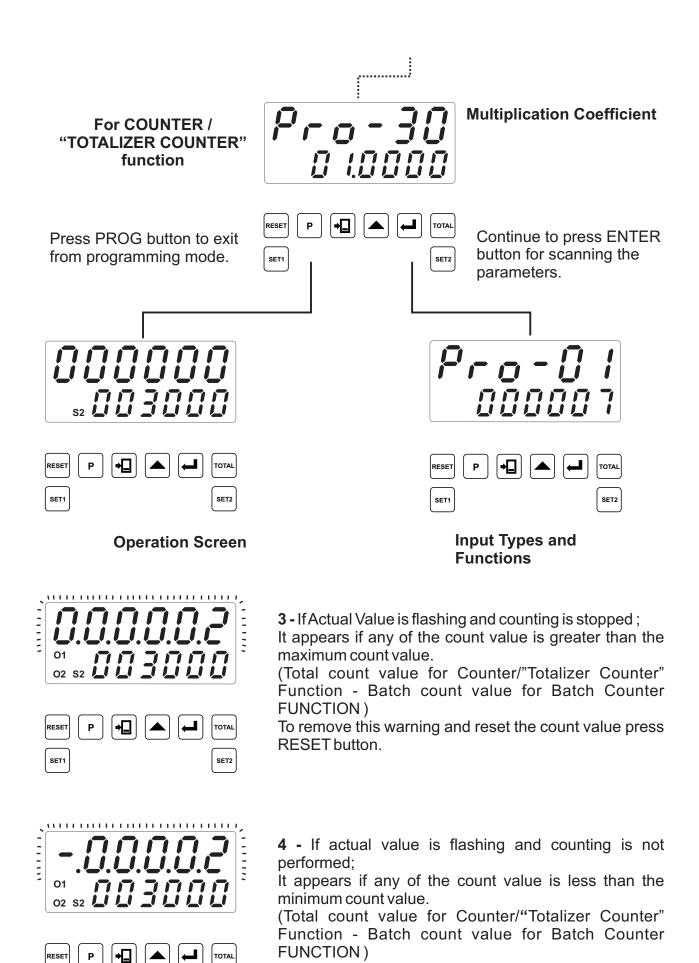
For details, refer to Section 2.8 "Selection of Operation Function and Input Type with DIP Switch".



**2 -** If the password is not 0, user can access to the parameters without entering the password and by pressing ENTER button.

User can see all parameters except for programming password parameter  $P_{-D}-P_{-D}$  but user can not do any changes in parameters. If password is entered for accessing to the parameters correctly, most significant digit of the parameter flashes. But if the password is not entered, flashing of the most significant digit is not realised.





RESET button.

SET2

SET1

To remove this warning and reset the count value press

10. Specifications

**Device Type** : Programmable Timer & Counter

**Housing & Mounting** : 72mm x 72mm x 87.5 DIN Size 43700 plastic housing for

panel mounting. Panel cut-out is 69x69mm.

Type-1 Enclosure Mounting. : IP65 at front, IP20 at rear.

**Protection Class** Weight : Approximately 0.25 Kg.

: Standard, indoor at an altitude of less than 2000 meters **Environmental Ratings** 

with none condensing humidity

Storage / Operating Temperature: -40 °C to +85 °C / 0 °C to +50 °C **Storage / Operating Humidity** : 90 % max. (None condensing)

Installation : Fixed installation

**Over Voltage Category** · 11

**Pollution Degree** : II, office or workplace, none conductive pollution

**Operating Conditions** : Continuous

Supply Voltage and Power : 100 - 240 VAC 50/60 Hz. (-15% / +10%) 6VA

24 VAC 50/60 Hz. (-15% / +10%) 6VA

24 VDC (-15% / +10%) 6W

**Electrical Characteristics** 

**Of Digital Inputs** : Rated voltage : 16 VDC @ 5mA

Maximum continuous permissible voltage: 30 VDC

Logic 1 minimum level: 3 VDC Logic 0 maximum level: 2 VDC

**Maximum Input Frequency** : For Counter / "Totalizer Counter" and Batch Counter;

If Pro-01 = 0, 1, 2; 6000Hz If  $P_{-0} - 0 = 3, 4; 5000 Hz$ If  $P_{-0} - 0 = 5$ , 6; 5000Hz If Pro-□! = 7;3000Hz

For Frequencymeter / Tachometer; 10kHz 

**Timer Accuracy** : Tolerance (25°C): +/- 30 ppm

Aging: +/- 5 ppm / year

Timing resolution dependent on selected time base Allow for electromechanical relay response time when

used (typically 30mSec)

:-Relay Output Module (5A@250VAC) **Optional Output Modules** 

> 100.000 operation (Full Load) -SSR Driver Output Module (Max. 26mA, 22VDC)

-Digital (Transistor) Output Module

(Max. 40mA@18VDC)

**Standard Communication** 

**Optional Communication** 

Module

: RS-232 Communication Module

Module : RS-485 Communication Module **Communication Protocol** : MODBUS-RTU, MODBUS-ASCII

**Process Display** : 10.8 mm Red 6 digit LED display **Set Display** : 8 mm Green 6 digit LED display

Led Indicators : SV1 (Set1 value), SV2 (Set2 value), O1 / 2 (Control

or Alarm Output ) LEDs

: UL Recognized Component(File Number: E 254103), **Approvals** 

EHE CE



Kessler-Ellis Products • 10 Industrial Way East, Eatontown, NJ 07724 • 732-935-1320 • www.KEPmLINE.com